Oriental motor

Brushless Motors

BLV Series
R Type

Modular Automation Compatible Products

Battery-Operated, Compact, and Lightweight Brushless Motors in the Era of Advancing Automation

NEW NEW

60 W/100 W/200 W/400 W

DC Input

High-Power, Compact Brushless Motors. Developed to Support the Design of Compact, Battery Driven Automation.

- Output: 60 W, 100 W, 200 W, 400 W
- Power Supply Input: 24～48 VDC*1
- Electromagnetic Brake Type Also Available

*1 400 W type is 48 VDC

What are "Modular Automation Compatible Products"?

"Modular Automation Compatible Products" is a product group with a shared concept of battery-operated, compact, and lightweight. Optimal for self-propelled equipment, these products meet the needs of flexible automation lines and mobile automation.

Modbus (RTU)
CANopen

Driver

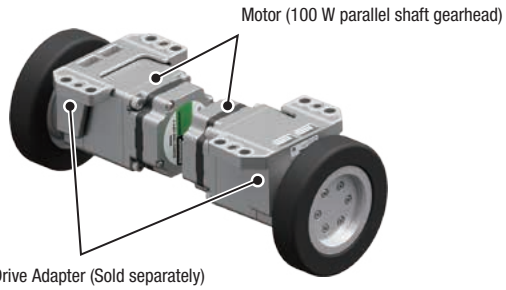
NEW CS Geared Motor

Compact, Lightweight, and High-Power Designed for Compact Equipment

- Compact and lightweight driver

  When connected to a motor, recognizes the output and covers all output with a single driver.

- Transportation robots for flat, transportable masses can be designed



Compatible with Modbus (RTU) and CANopen Communication

- Unified controllability of transportation robots, conveyors and other mechanisms

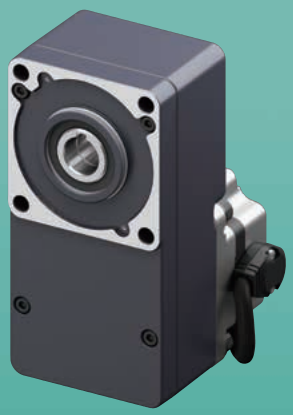
・Conveyor Drive Motor
(60 W **CS** geared motor)

Application: Autonomous transportation robot with belt conveyor

Smooth Motion, Current Position Acquisition and Positioning Operation are Possible

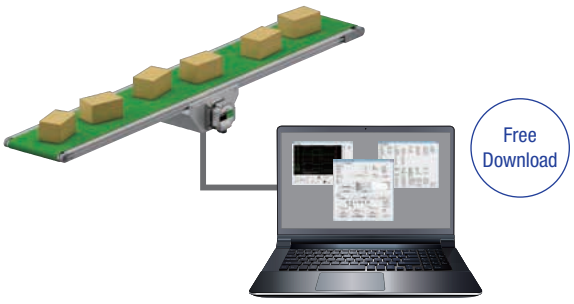
A Wider Range of Operating Voltage Supports Real World Battery Use

Parallel Shaft Gearhead



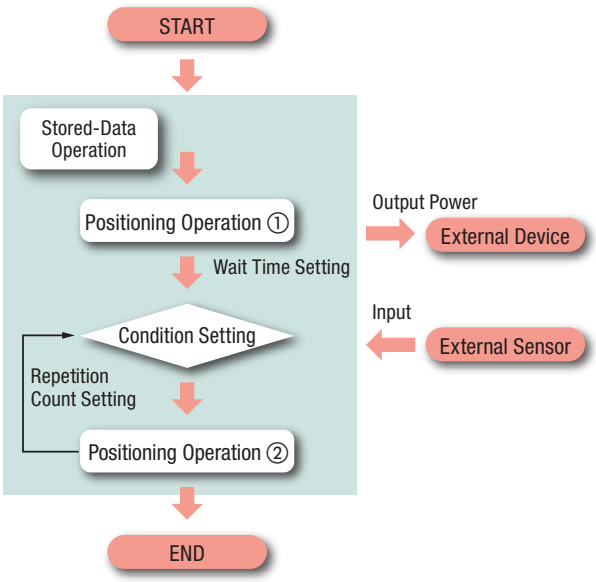
Hollow Shaft Flat Gearhead

Support from Startup and Operation to Maintenance with the Support Software **MEXE02**



Support Software **MEXE02**

Simplified Main Program Thanks to Sequence Function



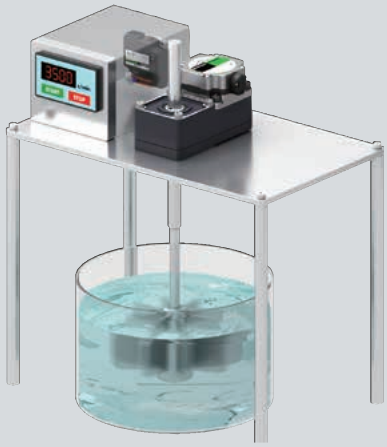
Various Applications

Transportation Robots

Transportation robots with a low floor design

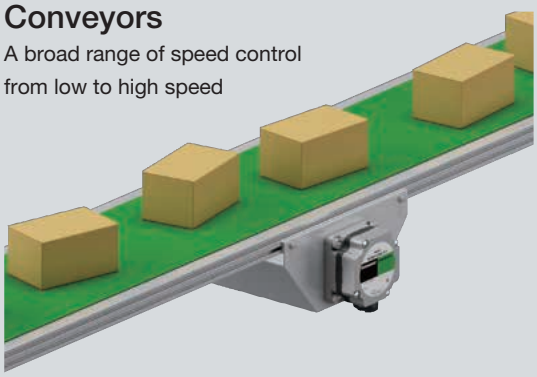
Agitators

Agitate at a stable speed, even if the viscosity (load) changes



Conveyors

A broad range of speed control
from low to high speed



Security Cameras

Quiet drive
Compact driver

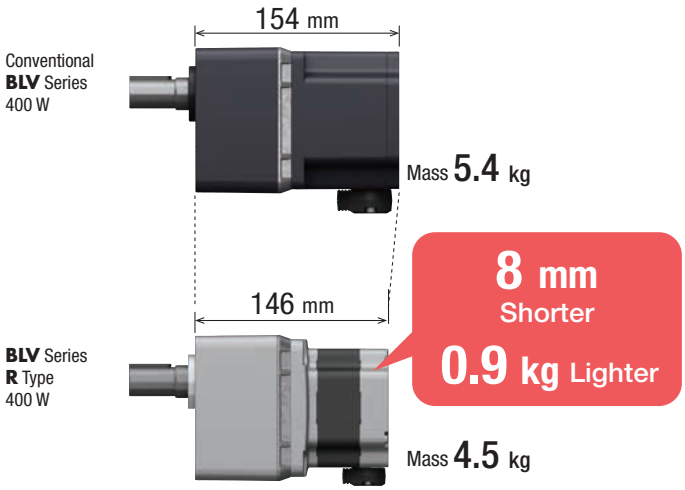
Compact, Lightweight, and High-Power

Designed for Compact Equipment

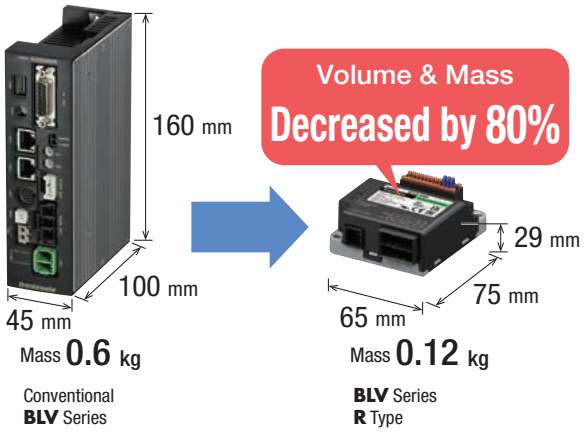
Compact and Lightweight

Both the motor and driver are significantly smaller and lighter.
The driver is approximately 80% smaller than the conventional product. The smaller driver saves valuable space in the automation equipment.

●Motor*



●Driver



*For a 400 W parallel shaft gearhead at a gear ratio of 30

Powerful

The new motor allows for larger inertia loads and heavier products to be transported when compared to the conventional product.
This also contributes to compact, high-power equipment design.

[Example of the design of a transportation robot]

●Conditions

BLV Series **R** Type Motor	Product Line	Hollow Shaft Flat Gearhead
	Output Power	400 W
	Gear Ratio	30
Driving Conditions	Vehicle Diameter	150 mm
	No. of Drive Wheels	2
	Acceleration Time	1 second

●Results

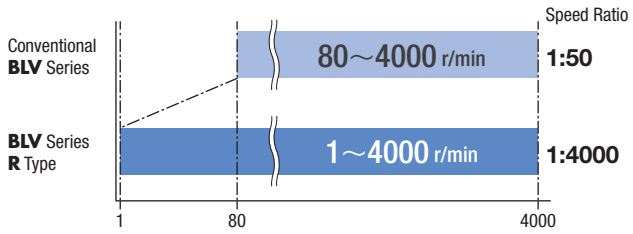
Max. Load Mass (Transportation robot mass + Load mass)	500 kg
Maximum Traveling Speed	0.7 m/sec

*The friction coefficient of the wheels is calculated at 0.1.

Wide Speed Range, Smooth Motion, Current Position and Position Feedback is Possible

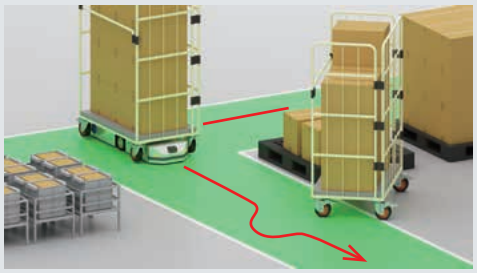
Broad Speed Control Range of 1～4000 r/min

Smooth startup and stopping is possible thanks to stable operation even in the low speed range from 1 r/min.



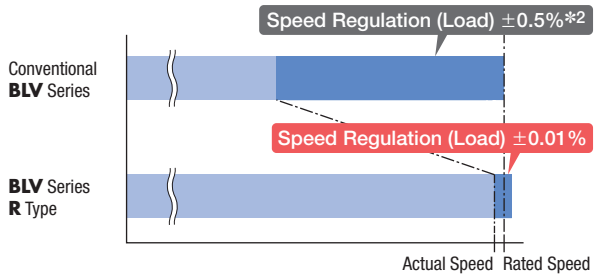
Benefit

•Smooth travel is possible, even with repeated start and stop operations.



High Speed Stability when Operated at High Speed

Operation at the set speed is possible even with the load fluctuation due to the speed regulation (load*1) of ±0.01%.



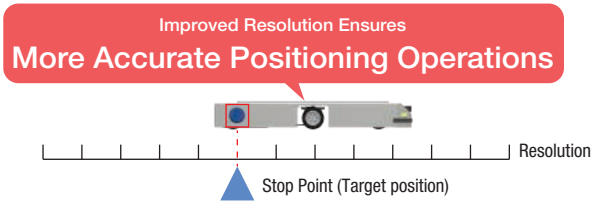
*1 Rate of change in speed when a constant load is applied

$$\text{Speed regulation} = \frac{\text{Actual speed} - \text{Command speed}}{\text{Actual speed}} \times 100\ (\%)$$

*2 ±0.2% for digital settings

Acquisition of Current Position and Positioning Operations are Possible

The current position can be acquired with enhanced motor feedback information.
Improved resolution allows the motor to stop at the target position.

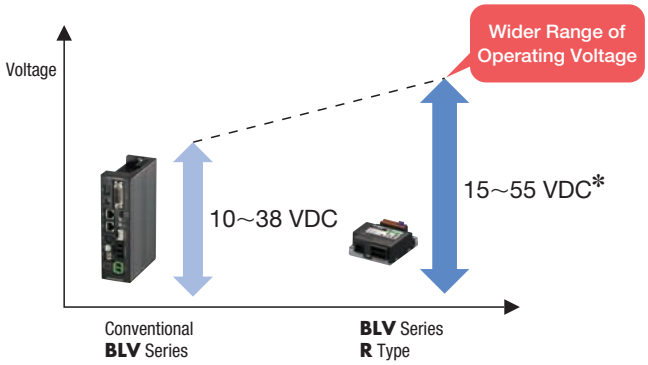


●The stopping accuracy during positioning operation is ±0.72° on the motor shaft and around 1～2° on the gearhead output shaft.

A Wider Range of Operating Voltage Supports

Real World Battery Use

Wider Range of Operating Voltage

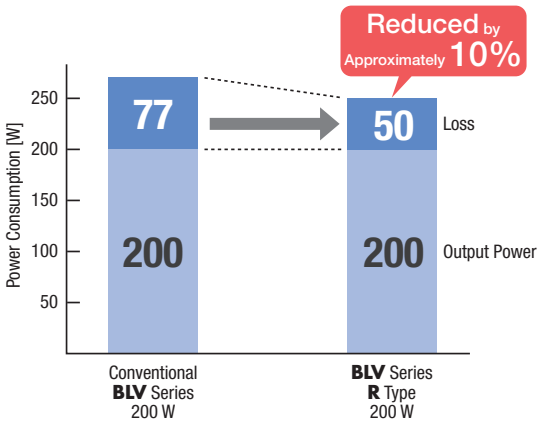


Benefit

- Compatible with 24~48 VDC batteries.
- Will not stop even if the battery voltage drops.
  Continues operating while limiting the speed and torque.

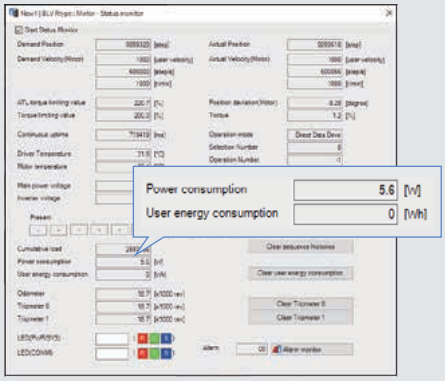
●The driver's overvoltage alarm threshold is 63 VDC.
✻400 W type is 48 VDC, operating voltage range is 30~55 VDC.

Power Consumption Reduced by 10%



Benefit

- Extended travel distance and time for transportation robots.
  The number of battery charges can also be decreased.
- Power consumption can be monitored via the Support Software **MEXE02** and communication.
  This is useful as charging reference.



Various Recommended Functions

Holding when Stopped is Possible without an Electromagnetic Brake

When the motor has stopped in an excitation state, it can be used as an electrical holding brake, even without a mechanical brake.

The motor enters an excitation state when the input signal "S-ON" is turned ON, and generates holding force. (Servo ON)
When the input signal "PLOOP-MODE" is turned ON, the position can be held with no deviation from the stop position.

Note

If the power supply to the driver is turned OFF, the holding force dissipates.
This cannot be used to prevent a fall during a power outage.

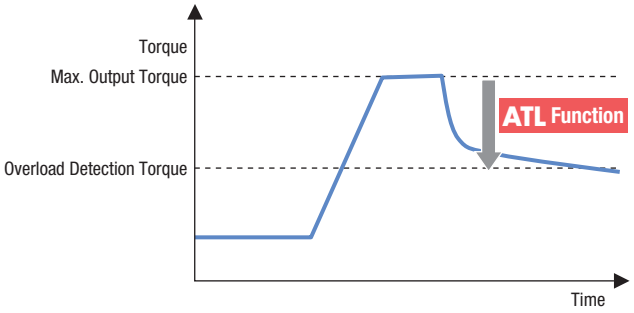
ATL Function that Automatically Limits Output Torque

The ATL function limits torque and ensures that the motor does not stop when an overload alarm occurs, even when torque continues to be output at a level at which an overload alarm is detected.

The motor will continue driving, even if an unexpected overload occurs*.

* Examples)
- Runs into an obstacle
- Sudden acceleration command
- Carrying a load exceeding the transportable mass

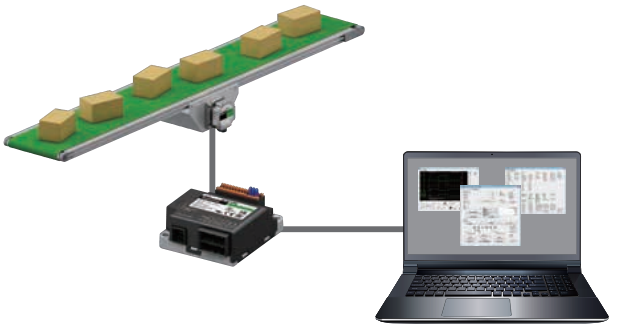
●Please disable the ATL function if the motor should stop when an alarm is output during overload.



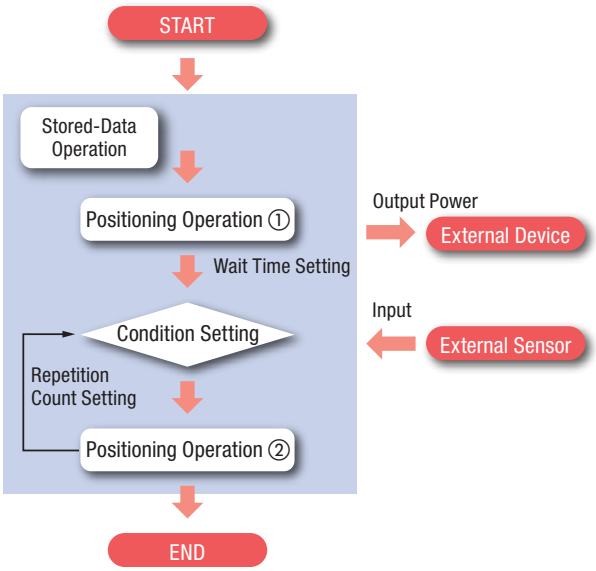
Simplified Main Program Thanks to Sequence Function

Can be used during stored-data operation, and comes with many sequence functions such as a timer setting for between operations and linked operation, conditional branching, and loop count. These help simplify the host system's sequence program.

●Stored-data settings (max. 256)
●Direct I/O (4 inputs, 2 outputs)
●Remote I/O (32 inputs, 32 outputs)

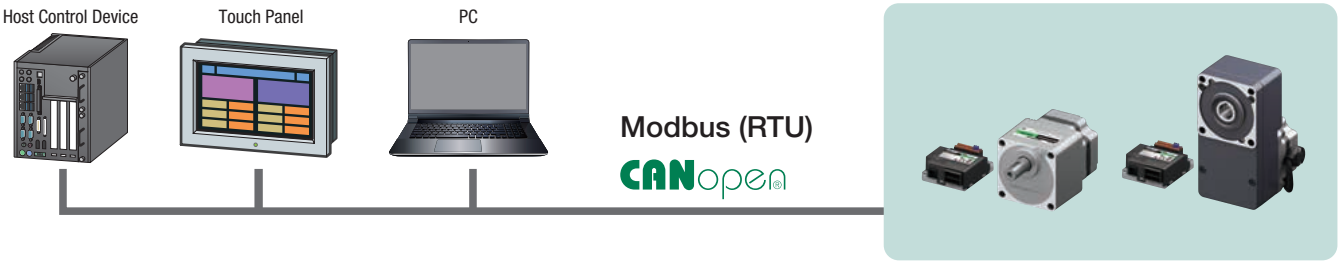


Support Software **MEXE02**



Compatible with Modbus (RTU) and CANopen Communication

The **BLV** Series **R** Type is compatible with the two interfaces of Modbus (RTU) and CANopen communication.



Main Functions with Modbus (RTU)

●Freely Create Operation Profiles - Direct Data Operation

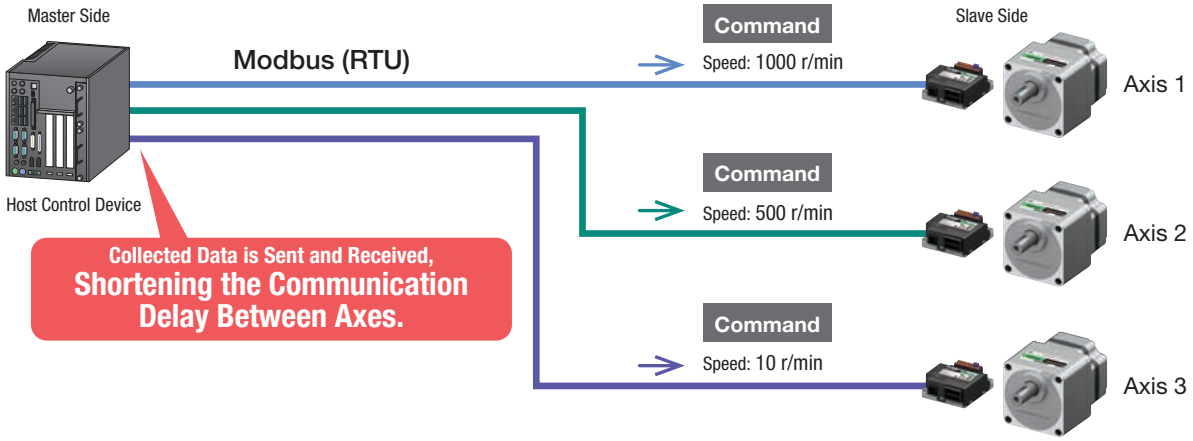
With Modbus (RTU) communication, data can be rewritten and operations can be started at the same time.

●Types of Operating Data

Operating Modes	Sets the operating mode.
Position	Sets the target position.
Speed	Sets the operating speed.
Acceleration Rate	Sets the acceleration time.
Deceleration Rate	Sets the deceleration time.
Torque Limiting Value	Sets the torque limiting value.

●Gather, Send, and Receive Data Across Different Axes - ID Share Mode

This function improves synchronization between axes with Modbus (RTU) communication.
Data collected from multiple axes can be sent and received, shortening the communication delay between axes.
It can also be used to send different commands to each axis at the same time.
This transmission method is unique to Oriental Motor.



Support from Startup and Operation to Maintenance

with the Support Software **MEXE02**

By using the Support Software **MEXE02**, data setting, actual operation, and confirmation via each monitor can be performed easily on a computer. The support software can be downloaded for free from the Oriental Motor website.

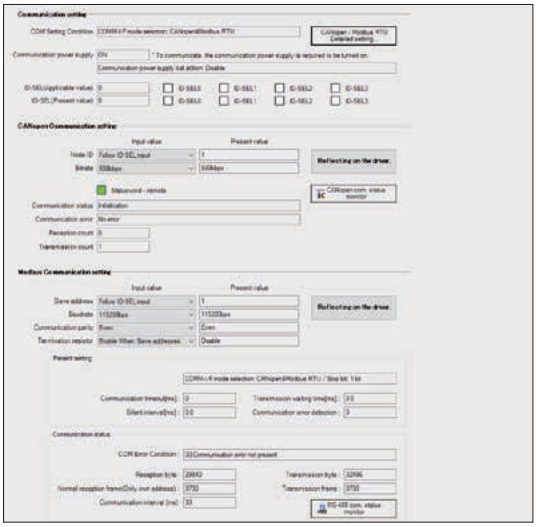
➜ https://www.orientalmotor.co.jp/download/software/mexe02_function/

Support Software
MEXE02

Startup Functions that Support Programing at Setup

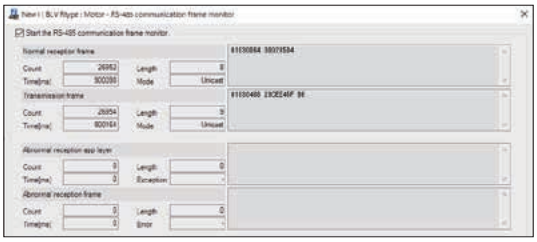
●Simple Settings

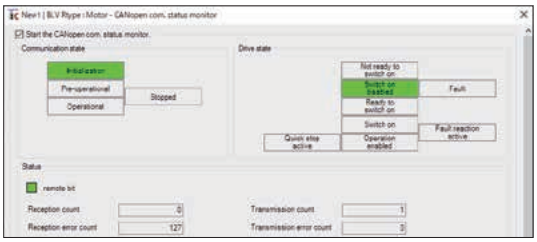
Various communication settings can be easily made using the "Simple communication settings".



●Communication Frame Monitoring, Communication Status Monitoring

All communication frames and statuses can be monitored. This is useful for host program startup and debugging.

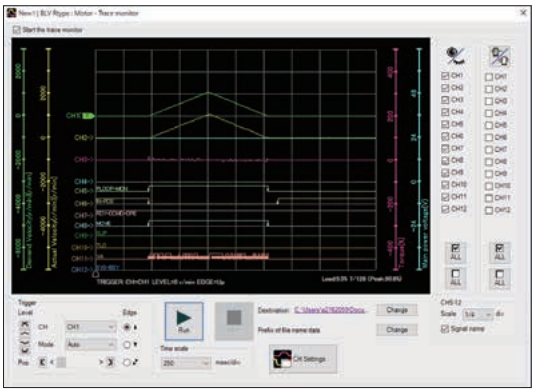




Operation Functions that Support Adjustments

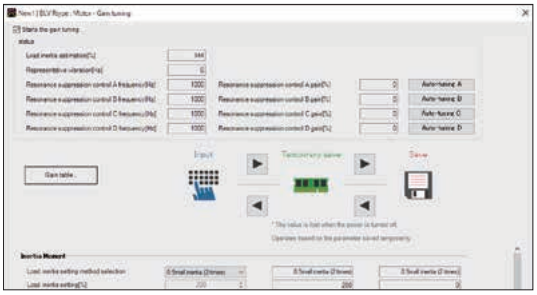
●Waveform Monitoring

The operating status of the motor (command speed, torque, I/O signal, etc.) can be checked like an oscilloscope.
Waveform measurement results can be saved as images and in CSV format.



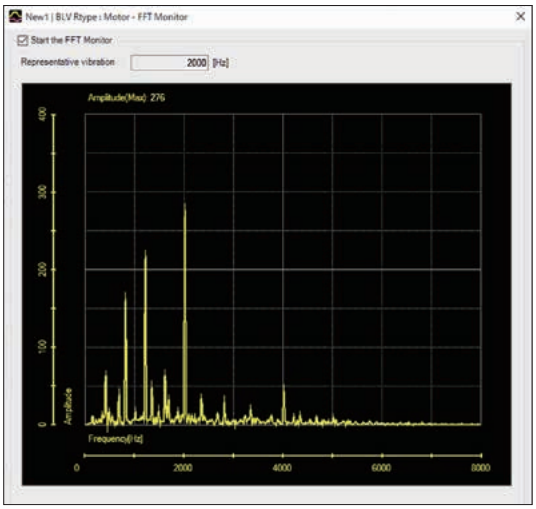
●Gain Tuning

Motor tracking can be adjusted according to the command.



●FFT Monitoring

Visualizes mechanical resonance by analyzing frequency using FFT analysis. Noise and vibration can be reduced by adjusting the "Resonance suppression parameter".



Maintenance Functions that Support Diagnostics and Maintenance

●Trace Monitoring

The operating status of the motor can be continuously measured for 24 hours or longer.
Data can be saved in CSV format.

Merit
Data is saved for a long period of time, making it easy to determine the cause of a problem.

Various Monitoring Functions

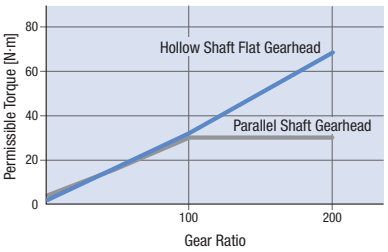
The Support Software **MEXE02** can also monitor various other types of information. For details, please see the Oriental Motor website.

Gearheads that Contribute to Space Saving Design

Higher Torque and Space Saving are Achieved with a Hollow Shaft Flat Gearhead

●Permissible Torque with no Saturation

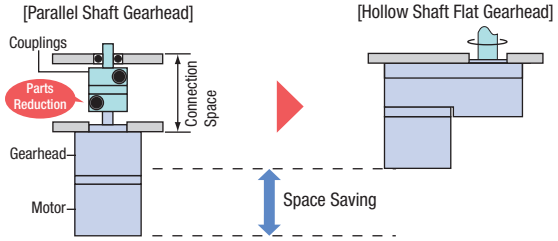
No saturation of permissible torque even at high gear ratios. This is useful for maximizing the motor torque.



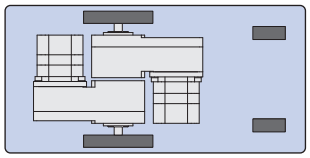
✻When frame size is 90 mm

●Space Saving and Cost Reduction

Direct connection to the drive shaft is possible without using a connecting part, which enables equipment space saving. The reduction in couplings, belts, pulleys, etc. also contributes to a decrease in the cost of parts and assembly work.



Example) Application in vehicle drive part
Staggered for a compact configuration.
✻Compatible with all types except 100 W



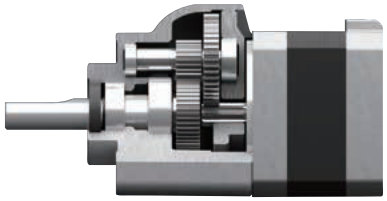
CS Geared Motor (60 W type) Makes Equipment Smaller and Lighter

CS geared motors feature increased load capacity, upgraded torque, and coaxial shaft.

●Contributes to Space Saving and Lighter Equipment

●Gear Structure with Coaxial Shaft

Large gears are arranged such that they will not escape from the central shaft, creating a gearhead with a coaxial shaft.



Product Line

Different motors, gearheads and cables are available based on the system requirements.

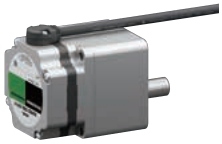
●Motors

Output Shaft Type	Output Power [W]	Frame Size [mm]	Gear Ratio	Electromagnetic Brake
Parallel Shaft Gearhead 	NEW 60	80	5～100	Not Equipped
	100	90	10～100	Equipped/ Not Equipped
	200	110		
	NEW 400		10～50	
Hollow Flat Gearhead 	NEW 60	80	5～200	Not Equipped
	100	90	10～200	Equipped/ Not Equipped
	200	104	10～100	
	NEW 400			
CS Geared Motor*1 	NEW 60	60	5～20	Not Equipped
Round Shaft Type 	NEW 60	60	–	Not Equipped
	100	90		Equipped/ Not Equipped
	200			
	NEW 400			

✻1 A geared motor in which the motor and gearhead are integrated.

✻2 0.3 m flexible connection cables are not available.

●2 motor cable drawing directions to choose from



Cable Output in the Side of the Output Shaft

Cable Output in the Opposite Side of the Output Shaft

●Driver

	Power Supply Voltage [VDC]	Output Power [W]
	DC24～48	60 100 200
	DC48	400

●Connection Cables / Flexible Connection Cables

◇60 W NEW

	Length [m]
	0.3*2, 1, 2, 3

◇100 W/200 W/400 W

	Length [m]
	1, 2, 3

●Power Supply Cable

	Length [m]
	0.6

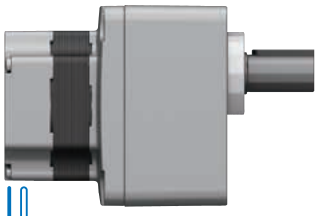
System Configuration

60 W

Motors, drivers, connection cables, and power supply cables are sold separately.

◉ Be sure to purchase
○ Purchase as needed

◉ Motor



Support Software **MEXE02**

To USB Port

●The Support Software **MEXE02** can be downloaded from the Oriental Motor website.

Not supplied.
USB Cable

◉ Driver

Host Control Device

Power Supply for Communication

Not supplied.

◉ Connection Cables / Flexible Connection Cables ➔ Page 43

●Please purchase a connection cable.

Max. Extension Length: 3.0 m

Not supplied.

DC Power Supply (Main power supply)

○ Peripheral Equipment for Motors

Mounting Brackets for Motor and Gearhead
➔ Page 44

Flexible Couplings
➔ Page 44

◉ Power Supply Cable
➔ Page 43

●System Configuration Example *Please contact us for price information

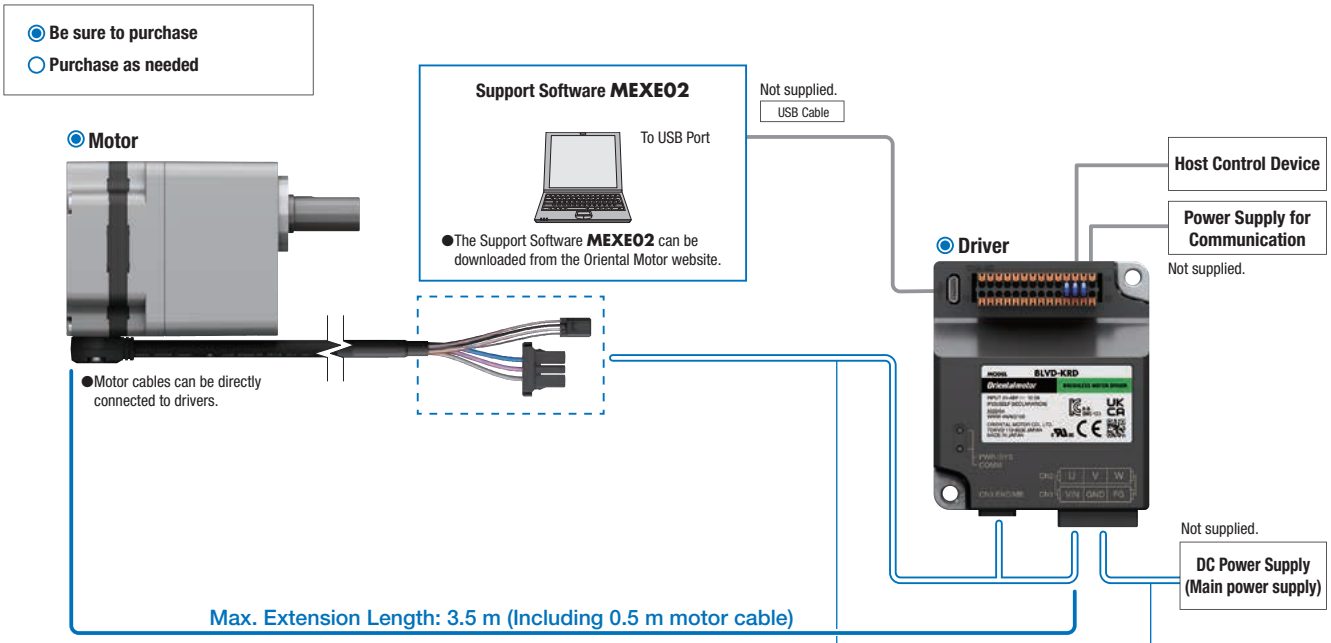
Motor		Driver		Cables	
				Connection Cable (1 m)	Power Supply Cable
BLMR460SHK-10		BLVD-KRD		CCM010B1ABF	LC03D06A
◉		◉		◉	◉

● The system configuration shown above is an example. Other combinations are also available.

●100 W, 200 W, 400 W

Motors, drivers, connection cables, and power supply cables are sold separately.

● Be sure to purchase
○ Purchase as needed



2 types of cable output direction are available for the motor.

Cable Output in the Side of the Output Shaft

Cable Output in the Opposite Side of the Output Shaft

○ Connection Cables / Flexible Connection Cables
➜ Page 43

● Power Supply Cable
➜ Page 43

○ Peripheral Equipment for Motors

Mounting Brackets for Motor and Gearhead
➜ Page 44

Flexible Couplings
➜ Page 44

○ Flange Drive Adapter ➜ Page 43

These products allow for greatly increased permissible load with the installation of a gearhead. For use with parallel shaft gearhead motors with an output power 100 W.

●System Configuration Example *Please contact us for price information

Motor	Driver	Cables		Peripheral Equipment
		Connection Cable (1 m)	Power Supply Cable	Flange Drive Adapter
BLMR5100K-10-F	BLVD-KRD	CCM010B1AAF	LC03D06A	AGD580B
◉	◉	○	◉	○

● The system configuration shown above is an example. Other combinations are also available.

Product Number

Motor

BLMR 6 200 S □ K M - 10 FR - F

① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ⑨ ⑩

①	Motor Type	**BLMR**: **BLV** Series **R** Type Motor
②	Frame Size	**2**: 60 mm **4**: 80 mm **5**: 90 mm **6**: 104 mm (110 mm for gearhead)
③	Output Power	**60**: 60 W **100**: 100 W **200**: 200 W **400**: 400 W
④	Identification Number	**S**
⑤	Motor Connection Method	**H**: Connector Type
⑥	Power Supply Voltage	**K**: DC Input
⑦	**M**: Type with Electromagnetic Brake	
⑧	Gear Ratio and Shaft Type	Number: Gearhead Gear Ratio **A**: Round Shaft Type
⑨	Gearhead Type	Blank: Parallel Shaft Gearhead **FR**: Hollow Shaft Flat Gearhead **CS**: **CS** Geared Motor
⑩	Cable Output Direction	**F**: Cable output in the side of the output shaft **B**: Cable output in the opposite side of the output shaft

Driver

BLVD - K R D

① ② ③ ④

①	Driver Type	**BLVD**: **BLV** Series Driver
②	Power Supply Voltage	**K**: DC Input
③	Type	**R** Type
④	Identification Number	**D**

Connection Cables / Flexible Connection Cables

CCM 010 B1AA F

① ② ③ ④

①	Cable Type	**CCM**: Connection Cable
②	Length	**003**: 0.3 m **010**: 1 m **020**: 2 m **030**: 3 m
③	Identification Number	**B1AA**, **B1AB**
④	**F**: Connection Cable **R**: Flexible Connection Cable	

Product Line

Please purchase the motor, driver, connection cable, and power supply cable separately.

●Motor

◇Parallel Shaft Gearhead

Output Power	Product Name	Gear Ratio
60 W	**BLMR460SHK-□**	**5**, **10**, **15**, **20**
		30, **50**, **100**
100 W	**BLMR5100K-□-■**	**10**, **15**, **20**
		30, **50**, **100**
200 W	**BLMR6200SK-□-■**	**10**, **15**, **20**
		30, **50**
		100
400 W	**BLMR6400SK-□-■**	**10**, **15**, **20**
		30, **50**

◇Hollow Shaft Flat Gearhead

Output Power	Product Name	Gear Ratio
60 W	**BLMR460SHK-□FR**	**5**, **10**, **15**, **20**
		30, **50**, **100**
		200
100 W	**BLMR5100K-□FR-■**	**10**, **15**, **20**
		30, **50**, **100**
		200
200 W	**BLMR6200SK-□FR-■**	**10**, **15**, **20**
		30, **50**, **100**
400 W	**BLMR6400SK-□FR-■**	**10**, **15**, **20**
		30, **50**, **100**

◇**CS** Geared Motor*

Output Power	Product Name	Gear Ratio
60 W	**BLMR260HK-□CS**	**5**, **10**, **15**, **20**

*A geared motor in which the motor and gearhead are integrated. The combination of motors and gearheads can cannot be changed.

◇Round Shaft Type

Output Power	Product Name
60 W	**BLMR260HK-A**
100 W	**BLMR5100K-A-■**
200 W	**BLMR5200K-A-■**
400 W	**BLMR5400K-A-■**

●Electromagnetic Brake Motor

◇Parallel Shaft Gearhead

Output Power	Product Name	Gear Ratio
100 W	**BLMR5100KM-□-■**	**10**, **15**, **20**
		30, **50**, **100**
200 W	**BLMR6200SKM-□-■**	**10**, **15**, **20**
		30, **50**
		100
400 W	**BLMR6400SKM-□-■**	**10**, **15**, **20**
		30, **50**

◇Hollow Shaft Flat Gearhead

Output Power	Product Name	Gear Ratio
100 W	**BLMR5100KM-□FR-■**	**10**, **15**, **20**
		30, **50**, **100**
		200
200 W	**BLMR6200SKM-□FR-■**	**10**, **15**, **20**
		30, **50**, **100**
400 W	**BLMR6400SKM-□FR-■**	**10**, **15**, **20**
		30, **50**, **100**

◇Round Shaft Type

Output Power	Product Name
100 W	**BLMR5100KM-A-■**
200 W	**BLMR5200KM-A-■**
400 W	**BLMR5400KM-A-■**

●Driver

Output Power	Product Name
60 W 100 W 200 W 400 W	**BLVD-KRD**

● A number indicating the gear ratio is specified where the box □ is located in the product name.
The letter **F** or **B** indicating the cable output direction is specified where the box ■ is located in the product name.

●Connection Cable

◇For 60 W

Length	Product Name
0.3 m	**CCM003B1ABF**
1 m	**CCM010B1ABF**
2 m	**CCM020B1ABF**
3 m	**CCM030B1ABF**

◇For 100 W, 200 W, and 400 W

Length	Product Name
1 m	**CCM010B1AAF**
2 m	**CCM020B1AAF**
3 m	**CCM030B1AAF**

●Power Supply Cable

Length	Product Name
0.6 m	**LC03D06A**

●Flexible Connection Cable

◇For 60 W

Length	Product Name
1 m	**CCM010B1ABR**
2 m	**CCM020B1ABR**
3 m	**CCM030B1ABR**

◇For 100 W, 200 W, and 400 W

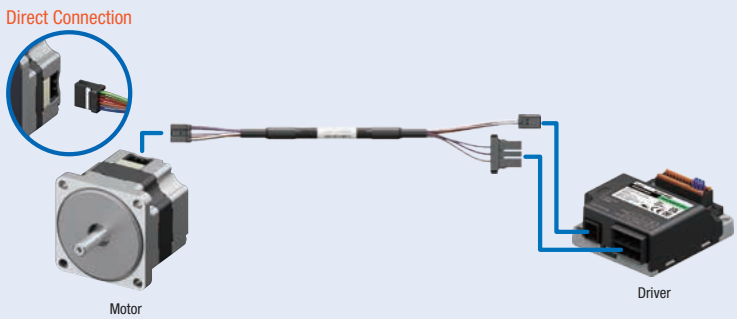
Length	Product Name
1 m	**CCM010B1AAR**
2 m	**CCM020B1AAR**
3 m	**CCM030B1AAR**

■Included Items

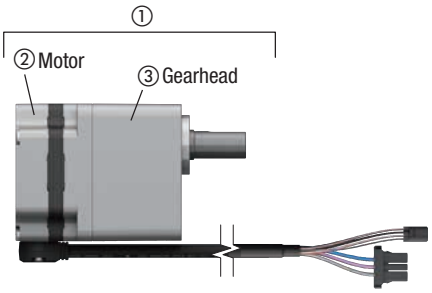
Type	Parallel Key	Safety Cover	Installation Screws
Parallel Shaft Gearhead	1	–	1 set
Hollow Shaft Flat Gearhead	1	1 set	1 set
CS Geared Motor	1	–	1 set
Round Shaft	–	–	–
Driver	–	–	–

Direct Connection (60 W)

The motor and driver can be connected with one cable.
Please purchase a connection cable.



List of Combinations



④ Driver

⑤ Connection Cable
Flexible Connection Cable

⑥ Power Supply Cable

Motor

Output Power	Type	Brushless Motors			Driver	Connection cable Flexible Connection Cable	Power Supply Cable
		Product Name	Components		Product Name	Product Name	Product Name
		①	②	③	④	⑤	⑥
60 W	Parallel Shaft Gearhead	**BLMR460SHK-□**	BLMR460SHK-GFV	GFV4G□	**BLVD-KRD**	**CCM003B1ABF** **CCM010B1AB◇** **CCM020B1AB◇** **CCM030B1AB◇**	**LC03D06A**
	Hollow Shaft Flat Gearhead	**BLMR460SHK-□FR**		GFS4G□FR			
	CS Geared Motor	**BLMR260HK-□CS**	–	–			
	Round Shaft Type	**BLMR260HK-A**	–	–			
100 W	Parallel Shaft Gearhead	**BLMR5100K-□-■**	BLMR5100K-GFV-■	GFV5G□		**CCM010B1AA◇** **CCM020B1AA◇** **CCM030B1AA◇**	
	Hollow Shaft Flat Gearhead	**BLMR5100K-□FR-■**		GFS5G□FR			
	Round Shaft Type	**BLMR5100K-A-■**	–	–			
200 W	Parallel Shaft Gearhead	**BLMR6200SK-□-■**	BLMR6200SK-GFV-■	GFV6G□			
	Hollow Shaft Flat Gearhead	**BLMR6200SK-□FR-■**		GFS6G□FR			
	Round Shaft Type	**BLMR5200K-A-■**	–	–			
400 W	Parallel Shaft Gearhead	**BLMR6400SK-□-■**	BLMR6400SK-GFV-■	GFV6G□			
	Hollow Shaft Flat Gearhead	**BLMR6400SK-□FR-■**		GFS6G□FR			
	Round Shaft Type	**BLMR5400K-A-■**	–	–			

Electromagnetic Brake Motor

Output Power	Type	Brushless Motors			Driver	Connection cable Flexible Connection Cable	Power Supply Cable
		Product Name	Components		Product Name	Product Name	Product Name
		①	②	③	④	⑤	⑥
100 W	Parallel Shaft Gearhead	**BLMR5100KM-□-■**	BLMR5100KM-GFV-■	GFV5G□	**BLVD-KRD**	**CCM010B1AA◇** **CCM020B1AA◇** **CCM030B1AA◇**	**LC03D06A**
	Hollow Shaft Flat Gearhead	**BLMR5100KM-□FR-■**		GFS5G□FR			
	Round Shaft Type	**BLMR5100KM-A-■**	–	–			
200 W	Parallel Shaft Gearhead	**BLMR6200SKM-□-■**	BLMR6200SKM-GFV-■	GFV6G□			
	Hollow Shaft Flat Gearhead	**BLMR6200SKM-□FR-■**		GFS6G□FR			
	Round Shaft Type	**BLMR5200KM-A-■**	–	–			
400 W	Parallel Shaft Gearhead	**BLMR6400SKM-□-■**	BLMR6400SKM-GFV-■	GFV6G□			
	Hollow Shaft Flat Gearhead	**BLMR6400SKM-□FR-■**		GFS6G□FR			
	Round Shaft Type	**BLMR5400KM-A-■**	–	–			

● A number indicating the gear ratio is specified where the box □ is located in the product name.
The letter **F** or **B** indicating the cable output direction is specified where the box ■ is located in the product name.
The letter **F** (connection cable) or **R** (flexible connection cable) is specified where the symbol ◇ is located in the product name.

Parallel Shaft Gearheads

60 W, 100 W, 200 W, 400 W

Specifications

Product Name				BLMR460SHK-□	BLMR5100K-□-■	BLMR6200SK-□-■	BLMR6400SK-□-■
	Motor	With Electromagnetic Brake		–	BLMR5100KM-□-■	BLMR6200SKM-□-■	BLMR6400SKM-□-■
	Driver			BLVD-KRD			
Rated Output Power			W	60	100	200	400
Power Supply Input	Rated Voltage		V	24–48 VDC			48 VDC
	Operating Voltage		V	15–55 VDC			30–55 VDC
	Rated Input Current		A	1.7 (48 V)～3.3 (24 V)	2.6 (48 V)～5.1 (24 V)	5.3 (48 V)～10.5 (24 V)	10.4
	Max. Input Current		A	5.5	10	18	16
Rated Speed			r/min	3000			
Speed Control Range*1				1～4000 r/min (Speed ratio 1:4000)			
Speed Regulation	Load			±0.01% or less: Conditions 0～rated torque, rated speed, rated voltage, normal ambient temperature			
	Voltage			±0.01% or less: Conditions Rated voltage, rated speed, no load, normal ambient temperature			
	Temperature			±0.01% or less: Conditions Operating ambient temperature 0～+40°C, rated speed, no load, rated voltage			
Resolution*1				0.01° (1 rotation: 36000 pulses)			
Electromagnetic Brake	Type			–	Power off activated type, automatically controlled by the driver		
	Static Friction Torque		N·m	–	0.319	0.637	1.27
Time Rating				Continuous	Continuous	Continuous	30 minutes*2

*1 Factory setting.

*2 Check the Speed – Torque Characteristics for details. ➜ Page 24

Gear Ratio				5	10	15	20	30	50	100*1
Rotation Direction		60/100 W		Same direction as motor				Opposite direction from motor		
		200/400 W		Same direction as motor				Opposite direction from motor		Same direction as motor
Output Shaft Speed [r/min]*2			1 r/min	0.2	0.1	0.067	0.05	0.033	0.02	0.01
			3000 r/min	600	300	200	150	100	60	30
			4000 r/min	800	400	267	200	133	80	40
Permissible Torque [N·m]		60 W	At 1～3000 r/min	0.86	1.7	2.6	3.4	4.9	8.2	16
			At 4000 r/min	0.43	0.86	1.3	1.7	2.5	4.1	8.3
		100 W	At 1～3000 r/min	-	2.9	4.3	5.7	8.2	13.7	27.4
			At 4000 r/min	-	2.2	3.2	4.3	6.2	10.3	20.6
		200 W	At 1～3000 r/min	-	5.7	8.6	11.5	16.4	27.4	51.6
			At 4000 r/min	-	4.1	6.1	8.1	11.6	19.4	36.5
		400 W	At 1～3000 r/min	-	11.4	17.1	22.9	32.8	55	-
			At 4000 r/min	-	8.6	12.9	17.2	24.6	41.1	-
Max. Instantaneous Torque [N·m]		60 W		1.7	3.4	5.2	6.9	9.9	16.4	20
		100 W		-	5.7	8.6	11.5	16.5	27.4	40
		200 W		-	11.5	17.2	22.9	32.9	55	100
		400 W		-	22.9	34.3	45	66	85	-
Permissible Inertia J [×10^{-4}kg·m^2]	When deceleration time is set*3	60 W		245	980	2205	3920	8820	24500	98000
		100 W		-	2300	5175	9200	20700	57500	230000
		200 W		-	3400	7650	13600	30600	85000	340000
		400 W		-	4500	10125	18000	40500	112500	-
	When immediately stopped*4	60 W		5.5	22	49.5	88	198	550	
		100 W		-	100	225	400	900	2500	
		200 W 400 W		-	200	450	800	1800	5000	
Permissible Radial Load [N]	From the end of the output shaft 10 mm	60 W	At 1～3000 r/min	200	300			450		
			At 4000 r/min	180	270			420		
		100 W	At 1～3000 r/min	-	400			500		
			At 4000 r/min	-	370			450		
		200 W 400 W	At 1～3000 r/min	-	550			1000		1400
			At 4000 r/min	-	500			900		1200
	From the end of the output shaft 20 mm	60 W	At 1～3000 r/min	250	350			550		
			At 4000 r/min	220	330			500		
		100 W	At 1～3000 r/min	-	500			650		
			At 4000 r/min	-	430			550		
		200 W 400 W	At 1～3000 r/min	-	800			1250		1700
			At 4000 r/min	-	700			1100		1400
Permissible Axial Load [N]		60 W		100						
		100 W		-	150					
		200 W 400 W		-	200			300		400

*1 The gear ratio of **100** is compatible with the 60 W type, 100 W type, and 200 W type.

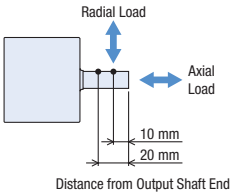
*2 The output shaft speed is the speed divided by the gear ratio.

*3 The maximum permissible inertia when the deceleration time is set to 0.1 seconds or higher. Please set the acceleration time so that the torque needed for acceleration/deceleration does not exceed the maximum instantaneous torque.

*4 Also applicable when the deceleration time is set to below 0.1 seconds.

● The values correspond to each specification and characteristics of a stand-alone motor.
A number indicating the gear ratio is specified where the box □ is located in the product name.
The letter **F** or **B** indicating the cable output direction is specified where the box ■ is located in the product name.

◇Load Position



■Speed – Torque Characteristics

➜ Page 24

■Dimensions

Motor ➜ Pages 26 and 27
Electromagnetic Brake Motor ➜ Pages 33 and 34
Driver ➜ Page 40

Hollow Shaft Flat Gearhead

60 W, 100 W, 200 W, 400 W

Specifications

Product Name				BLMR460SHK-□FR	BLMR5100K-□FR-■	BLMR6200SK-□FR-■	BLMR6400SK-□FR-■
	Motor	With Electromagnetic Brake		–	BLMR5100KM-□FR-■	BLMR6200SKM-□FR-■	BLMR6400SKM-□FR-■
	Driver			BLVD-KRD			
Rated Output Power			W	60	100	200	400
Power Supply Input	Rated Voltage		V	24–48 VDC			48 VDC
	Operating Voltage		V	15–55 VDC			30–55 VDC
	Rated Input Current		A	1.7 (48 V)～3.3 (24 V)	2.6 (48 V)～5.1 (24 V)	5.3 (48 V)～10.5 (24 V)	10.4
	Max. Input Current		A	5.5	10	18	16
Rated Speed			r/min	3000			
Speed Control Range*1				1～4000 r/min (Speed ratio 1:4000)			
Speed Regulation	Load			±0.01% or less: Conditions 0～rated torque, rated speed, rated voltage, normal ambient temperature			
	Voltage			±0.01% or less: Conditions Rated voltage, rated speed, no load, normal ambient temperature			
	Temperature			±0.01% or less: Conditions Operating ambient temperature 0～+40°C, rated speed, no load, rated voltage			
Resolution*1				0.01° (1 rotation: 36000 pulses)			
Electromagnetic Brake	Type			–	Power off activated type, automatically controlled by the driver		
	Static Friction Torque		N·m	–	0.319	0.637	1.27
Time Rating				Continuous	Continuous	Continuous	30 minutes*2

*1 Factory setting.

*2 Check the Speed – Torque Characteristics for details. ➜ Page 24

Gear Ratio				5	10	15	20	30	50	100	200
Output Shaft Speed [r/min]*1			1 r/min	0.2	0.1	0.067	0.05	0.033	0.02	0.01	0.005
			3000 r/min	600	300	200	150	100	60	30	15
			4000 r/min	800	400	267	200	133	80	40	20
Permissible Torque [N·m]		60 W	At 1～3000 r/min	0.81	1.6	2.4	3.2	4.9	8.1	16.2	32.5
			At 4000 r/min	0.41	0.82	1.2	1.6	2.4	4.1	8.2	16.3
		100 W	At 1～3000 r/min	-	2.7	4.1	5.4	8.1	13.6	27.1	54
			At 4000 r/min	-	2.0	3.0	4.1	6.1	10.2	20.3	40.6
		200 W	At 1～3000 r/min	-	5.4	8.1	10.8	16.2	27	54	–
			At 4000 r/min	-	3.8	5.7	7.7	11.5	19.1	38.3	–
		400 W	At 1～3000 r/min	-	10.8	16.2	21.6	32.4	54	108	–
			At 4000 r/min	-	8.1	12.2	16.2	24.4	40.6	81	–
Max. Instantaneous Torque [N·m]		60 W		1.6	3.2	4.9	6.5	9.7	16.2	32.5	51
		100 W		-	5.4	8.1	10.8	16.3	27.1	54	85
		200 W		-	10.8	16.2	21.7	32.5	54	108	-
		400 W		-	21.6	32.4	43.2	65	108	167	-
Permissible Inertia J [×10^{-4}kg·m^2]	When deceleration time is set*2	60 W		245	980	2205	3920	8820	24500	98000	392000
		100 W		-	2300	5175	9200	20700	57500	230000	920000
		200 W		-	3400	7650	13600	30600	85000	340000	-
		400 W		-	4500	10125	18000	40500	112500	450000	-
	When immediately stopped*3	60 W		5.5	22	49.5	88	198	550		
		100 W		-	100	225	400	900	2500		
		200 W 400 W		-	200	450	800	1800	5000		-
Permissible Radial Load [N]*4	From installation surface 10 mm	60 W	At 1～3000 r/min	800		1200					
			At 4000 r/min	730		1100					
		100 W	At 1～3000 r/min	-	900	1300		1500			
			At 4000 r/min	-	820	1200		1400			
		200 W 400 W	At 1～3000 r/min	-	1230	1680		2040			-
			At 4000 r/min	-	1130	1550		1900			-
	From installation surface 20 mm	60 W	At 1～3000 r/min	660		1000					
			At 4000 r/min	600		910					
		100 W	At 1～3000 r/min	-	770	1110		1280			
			At 4000 r/min	-	700	1020		1200			
		200 W 400 W	At 1～3000 r/min	-	1070	1470		1780			-
			At 4000 r/min	-	990	1360		1660			-
Permissible Axial Load [N]		60 W		400							
		100 W		-	500						
		200 W 400 W		-	800						-

*1 The output shaft speed is the speed divided by the gear ratio.

*2 The maximum permissible inertia when the deceleration time is set to 0.1 seconds or higher. Please set the acceleration time so that the torque needed for acceleration/deceleration does not exceed the maximum instantaneous torque.

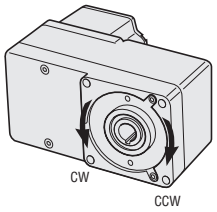
*3 Also applicable when the deceleration time is set to below 0.1 seconds.

*4 The radial load at each distance can also be calculated with a formula. ➜ Page 42

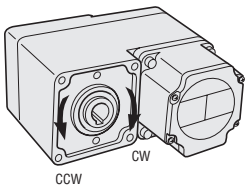
● The values correspond to each specification and characteristics of a stand-alone motor.
A number indicating the gear ratio is specified where the box □ is located in the product name.
The letter **F** or **B** indicating the cable output direction is specified where the box ■ is located in the product name.

◇Rotation Direction

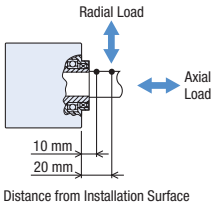
•Viewed from front face



•Viewed from back face



◇Load Position



■Speed – Torque Characteristics

➜ Page 24

■Dimensions

Motor ➜ Pages 28～30
Electromagnetic Brake Motor ➜ Pages 35～37
Driver ➜ Page 40

CS Geared Motor 60 W

Specifications

Product Name	Motor		BLMR260HK-□CS
	Driver		BLVD-KRD
Rated Output Power		W	60
Power Supply Input	Rated Voltage	V	24–48 VDC
	Operating Voltage	V	15–55 VDC
	Rated Input Current	A	1.7 (48 V)～3.3 (24 V)
	Max. Input Current	A	5.5
Rated Speed		r/min	3000
Speed Control Range*			1～4000 r/min (Speed ratio 1:4000)
Speed Regulation	Load		±0.01% or less: Conditions 0～rated torque, rated speed, rated voltage, normal ambient temperature
	Voltage		±0.01% or less: Conditions Rated voltage, rated speed, no load, normal ambient temperature
	Temperature		±0.01% or less: Conditions Operating ambient temperature 0～+40°C, rated speed, no load, rated voltage
Resolution*			0.01° (1 rotation: 36000 pulses)
Time Rating			Continuous

*Factory setting.

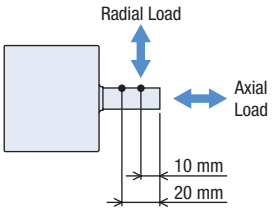
Gear Ratio			5	10	15	20
Rotation Direction			Same direction as motor			
Output Shaft Speed [r/min]*1		1 r/min	0.2	0.1	0.067	0.05
		3000 r/min	600	300	200	150
		4000 r/min	800	400	267	200
Permissible Torque [N·m]		At 1～3000 r/min	0.86	1.7	2.6	3.4
		At 4000 r/min	0.43	0.86	1.3	1.7
Max. Instantaneous Torque [N·m]			1.7	3.4	5.2	6.9
Permissible Inertia J [×10^{-4}kg·m^2]	When deceleration time is set*2		245	980	2205	3920
	When immediately stopped*3		3.1	12.4	28	49.6
Permissible Radial Load [N]	From the end of the output shaft 10 mm	At 1～3000 r/min	150	200		
		At 4000 r/min	130	180		
	From the end of the output shaft 20 mm	At 1～3000 r/min	190	260		
		At 4000 r/min	170	230		
Permissible Axial Load [N]			70			

*1 The output shaft speed is the speed divided by the gear ratio.

*2 The maximum permissible inertia when the deceleration time is set to 0.1 seconds or higher. Please set the acceleration time so that the torque needed for acceleration/deceleration does not exceed the maximum instantaneous torque.

*3 Also applicable when the deceleration time is set to below 0.1 seconds.

◇Load Position



Speed – Torque Characteristics

➜ Page 24

Dimensions

Motor ➜ Page 31
Driver ➜ Page 40

● The values correspond to each specification and characteristics of a stand-alone motor.
A number indicating the gear ratio is specified where the box □ is located in the product name.

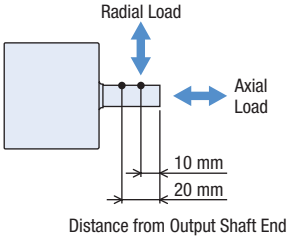
Round Shaft 60 W, 100 W, 200 W, 400 W

Specifications

Product Name				BLMR260HK-A	BLMR5100K-A-□	BLMR5200K-A-□	BLMR5400K-A-□
	Motor	With Electromagnetic Brake		–	BLMR5100KM-A-□	BLMR5200KM-A-□	BLMR5400KM-A-□
	Driver			BLVD-KRD			
Rated Output Power			W	60	100	200	400
Power Supply Input	Rated Voltage		V	24–48 VDC			48 VDC
	Operating Voltage		V	15–55 VDC			30–55 VDC
	Rated Input Current		A	1.7 (48 V)～3.3 (24 V)	2.6 (48 V)～5.1 (24 V)	5.3 (48 V)～10.5 (24 V)	10.4
	Max. Input Current		A	5.5	10	18	16
Rated Speed			r/min	3000			
Speed Control Range*1				1～4000 r/min (Speed ratio 1:4000)			
Rated Torque			N·m	0.191	0.319	0.637	1.27
Maximum Instantaneous Torque			N·m	0.382 (200%)	0.704 (220%)	1.34 (210%)	2.54 (200%)
Rotor Inertia J			$\times 10^{-4}$kg·m^2	0.098	0.252 (0.267)*2	0.499 (0.514)*2	0.737 (0.751)*2
Permissible Inertia J			$\times 10^{-4}$kg·m^2	9.8	23	34	45
Permissible Radial Load	From the end of the output shaft 10 mm		N	70	150		
	From the end of the output shaft 20 mm		N	100	170		
Permissible Axial Load			N	15	25		
Speed Regulation	Load			±0.01% or less: Conditions 0～rated torque, rated speed, rated voltage, normal ambient temperature			
	Voltage			±0.01% or less: Conditions Rated voltage, rated speed, no load, normal ambient temperature			
	Temperature			±0.01% or less: Conditions Operating ambient temperature 0～+40°C, rated speed, no load, rated voltage			
Resolution*1				0.01° (1 rotation: 36000 pulses)			
Electromagnetic Brake	Type			–	Power off activated type, automatically controlled by the driver		
	Static Friction Torque		N·m	–	0.319	0.637	1.27
Time Rating				Continuous	Continuous	Continuous	30 minutes*3

*1 Factory setting.
*2 The brackets ( ) indicate the specifications for the electromagnetic brake motor.
*3 Check the Speed – Torque Characteristics for details. ➜ Page 24

◇Load Position

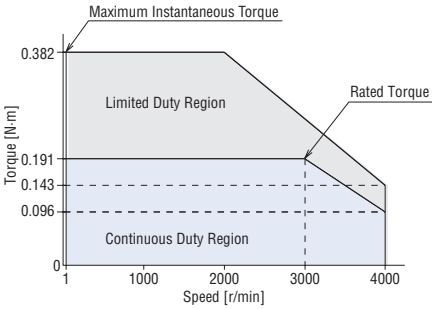


● The letter **F** or **B** indicating the cable output direction is specified where the box □ is located in the product name.

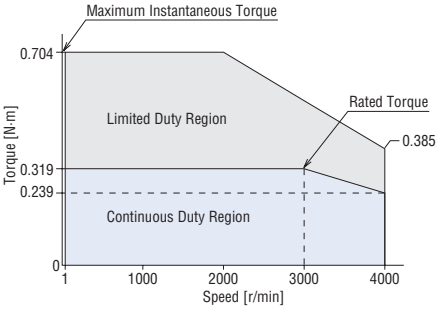
Speed – Torque Characteristics

Continuous Duty Region: Continuous operation is possible in this region.
Limited Duty Region: This region is used primarily when accelerating.

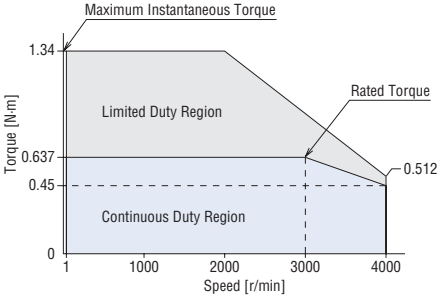
60 W



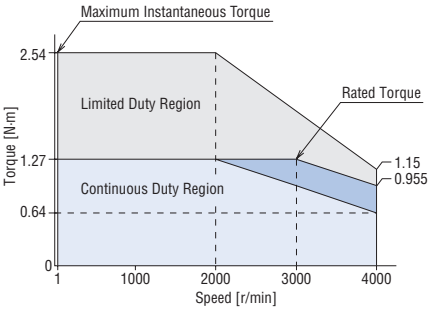
100 W



200 W



400 W



- The values correspond to each specification and characteristics of a stand-alone motor. The speed - torque characteristics show the values when rated voltage is applied.
- ▭ is the region with a time rating of 30 minutes. Operation for more than 30 minutes may be possible depending on the ambient temperature and heat radiation conditions.

Dimensions

Motor ➜ Pages 31 and 32
Electromagnetic Brake Motor ➜ Pages 38 and 39
Driver ➜ Page 40

Common Specifications

Item	Specifications
Input Signals	4 points, Photocoupler Input Mode
Output Signals	2 points, Photocoupler and Open-Collector Output
Main Operation Functions	Continuous Operation, Positioning Operation, JOG Operation, Return-to-Home Operation
Operating Data Setting Number	256 Points
Setting Tool	Support Software **MEXE02**
Maximum Extension Length	Motor and Driver Distance: 3.5 m* (when a connection cable sold separately is used)

*3.0 m for the 60 W type.

Communication Specifications

Power Supply for Communication

Power Supply Current Capacitance	Input Power Supply Voltage
0.2 A min.	24–48 VDC

RS-485 Communication Specifications

Electrical Characteristics	Complies with EIA-485. The maximum total extension length of the communication cable is 10 m when using twisted-pair wires. *
Communication Mode	Half duplex Start-stop synchronization (data: 8 bits, stop bit: 1 bit or 2 bits, parity: none, even, or odd)
Baud Rate	Select from 9,600 bps, 19,200 bps, 38,400 bps, 57,600 bps, 115,200 bps, and 230,400 bps (initial value)
Protocol	Modbus RTU Mode
Connection Type	Up to 31 units can be connected to a single host system.

*If noise generated by the motor cable or power supply cable causes a problem with the specific wiring or layout, shield the cable or use ferrite cores.

CANopen Communication Specifications

Electrical Characteristics	ISO 11898-compliant Use a CAN-BUS cable.
Communication Protocol	CANopen
Communication Profile	CiA DS301 Version 4.2.0-compliant
Device Profile	CiA DSP402 Version 4.0.0-compliant
Node ID	1～127
Bit Rate	Select from 1 Mbps, 800 kbps, 500 kbps (initial value), 250 kbps, 125 kbps, 50 kbps, 20 kbps, and 10 kbps
Max. Bus Length	25 m (Max. bus length at 1 Mbps)
Communication Objects	NMT (Network Management) SDO (Service Data Object: 1 SDO server) PDO (Process Data Object: 4 Receive-PDO, 4 Transmit-PDO) EMCY (Emergency Object) SYNC (Synchronization Object)
Operation Modes	Profile velocity mode (pv) Profile position mode (pp) Homing mode (hm)

General Specifications

Item		Motor	Driver
Insulation Resistance		100 MΩ or more when a 500 VDC megger is applied between the windings and the case after continuous operation*1 under normal ambient temperature and humidity.	100 MΩ or more when 500 VDC megger is applied between the heat sink and the main power supply input terminal after continuous operation under normal ambient temperature and humidity.
Dielectric Strength		Sufficient to withstand 0.5 kVAC at 50 Hz applied between the windings and the case for 1 minute after continuous operation*1 under normal ambient temperature and humidity.	Sufficient to withstand 0.5 kVAC at 50 Hz applied between the heat sink and the main power supply input terminal for 1 minute after continuous operation under normal ambient temperature and humidity.
Temperature Rise		The temperature rise of the windings is 60°C max. and that of the case surface is 50°C max.*2, measured by the thermocouple method after rated continuous operation*1 under normal ambient temperature and humidity.	The temperature rise of the heat sink is 50°C max., measured by the thermocouple method after rated continuous operation under normal ambient temperature and humidity.
Operating Environment	Ambient Temperature	0～+40°C (Non-freezing)	0～+40°C (Non-freezing)*3
	Ambient Humidity	85% max. (Non-condensing)	
	Altitude	Up to 1000 m above sea level	
	Atmosphere	No corrosive gases or dust. Should not be exposed to oil. Cannot be used in a radioactive area, magnetic field, vacuum, or other special environments.	
	Vibration	Not subject to continuous vibration or excessive shock In conformance with JIS C 60068-2-6, "Sine-wave vibration test method" Frequency Range: 10～55 Hz, Half Amplitude: 0.15 mm Sweep Direction: 3 directions (X, Y, Z) Number of Sweeps: 20 times	
Storage Condition*4	Ambient Temperature	−20～+70°C (Non-freezing)	−25～+70°C (Non-freezing)
	Ambient Humidity	85% max. (Non-condensing)	
	Altitude	Up to 3000 m above sea level	
	Atmosphere	No corrosive gases or dust. Should not be exposed to water or oil. Cannot be used in a radioactive area, magnetic field, vacuum, or other special environments.	
Thermal Class		UL/CSA Standards: 105 (A), EN Standards: 120 (E)	–
Degree of Protection		IP40	IP20

*1 30 minutes rating for the 400 W type

*2 For the round shaft type, install on a heat sink (material: aluminum) of the following size so that the surface temperature of the motor case does not exceed 90°C.
60 W type: 135×135 mm, thickness 5 mm, 100 W type: 165×165 mm, thickness 5 mm, 200 W type: 200×200 mm, thickness 5 mm, 400 W type: 250×250 mm, thickness 6 mm

*3 Install the driver to a location that has the same heat radiation capability as an aluminum metal plate.
200×200 mm, thickness 2 mm

*4 The storage condition applies to short periods such as the period during transport.

Note

- Do not measure insulation resistance or perform a dielectric strength test while the motor and driver are connected.

■Dimensions (Unit = mm)

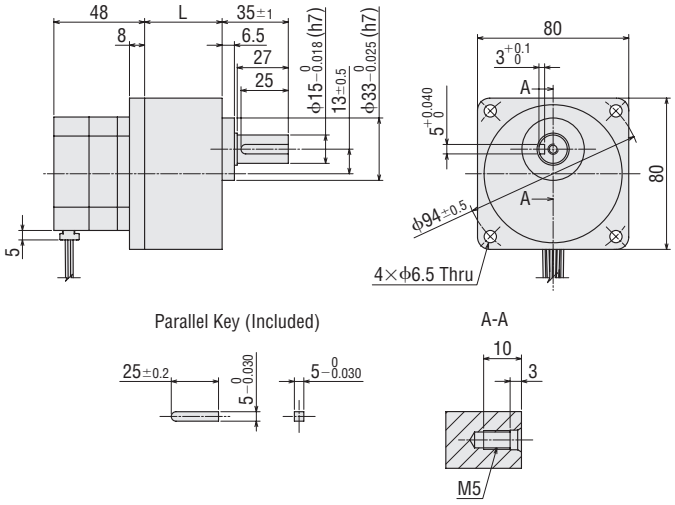
- Check "■Included" for the products that include the installation screws.
  Included ➜ Page 16/Installation Screw Dimensions ➜ Page 41
- A number indicating the gear ratio is specified where the box □ is located in the product name.
  The letter **F** (output in the side of the output shaft) or **B** (output in the opposite side of the output shaft) indicating the cable output direction is specified where the box ■ is located in the product name.

●Motor

◇Parallel Shaft Gearhead • 60 W

2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	2D CAD
BLMR460SHK-□	BLMR460SHK-GFV	GFV4G□	**5~20**	41	1.2	A1869A
			30~100	46	1.3	A1869B

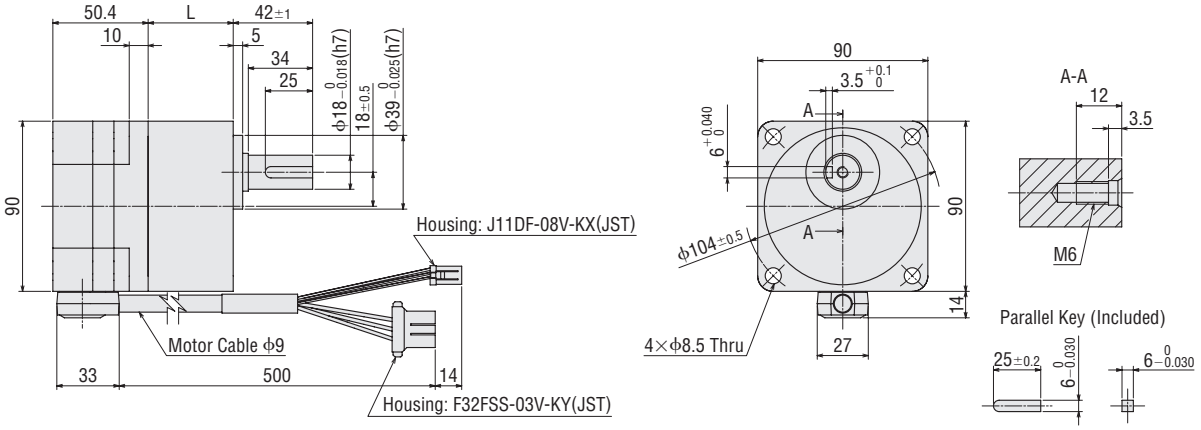


◇Parallel Shaft Gearhead • 100 W

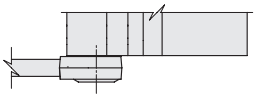
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	2D CAD	
						Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR5100K-□-■	BLMR5100K-GFV-■	GFV5G□	**10~20**	45	2.05	A1808A_F	A1808A_B
			30~100	58	2.4	A1808B_F	A1808B_B

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft

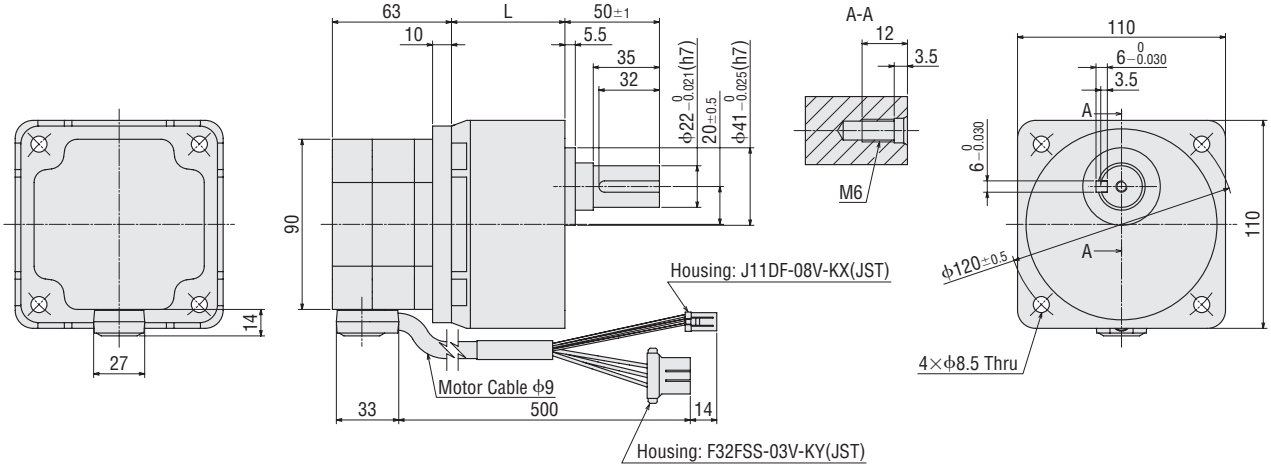


◇Parallel Shaft Gearhead • 200 W

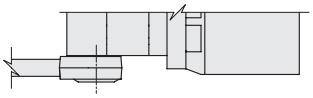
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	2D CAD	
						Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR6200SK-□-■	BLMR6200SK-GFV-■	GFV6G□	**10**～**20**	60	3.6	A1814A_F	A1814A_B
			30, **50**	72	4.1	A1814B_F	A1814B_B
			100	86	4.7	A1814C_F	A1814C_B

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft

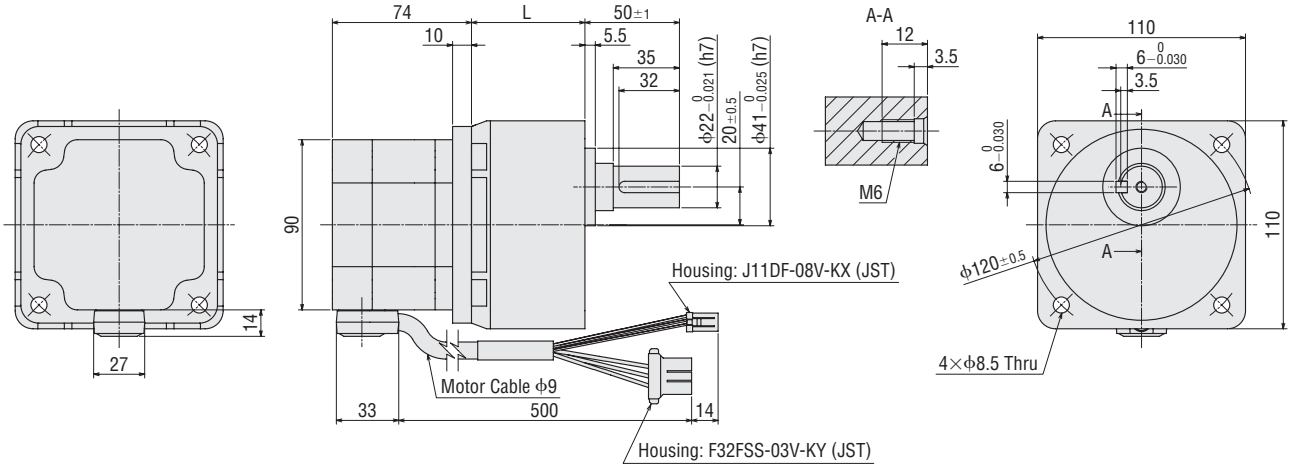


◇Parallel Shaft Gearhead • 400 W

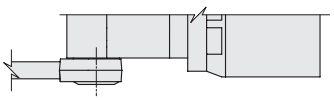
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	2D CAD	
						Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR6400SK-□-■	BLMR6400SK-GFV-■	GFV6G□	**10**～**20**	60	4.0	A1857A_F	A1857A_B
			30, **50**	72	4.5	A1857B_F	A1857B_B

•Cable output in the side of the output shaft



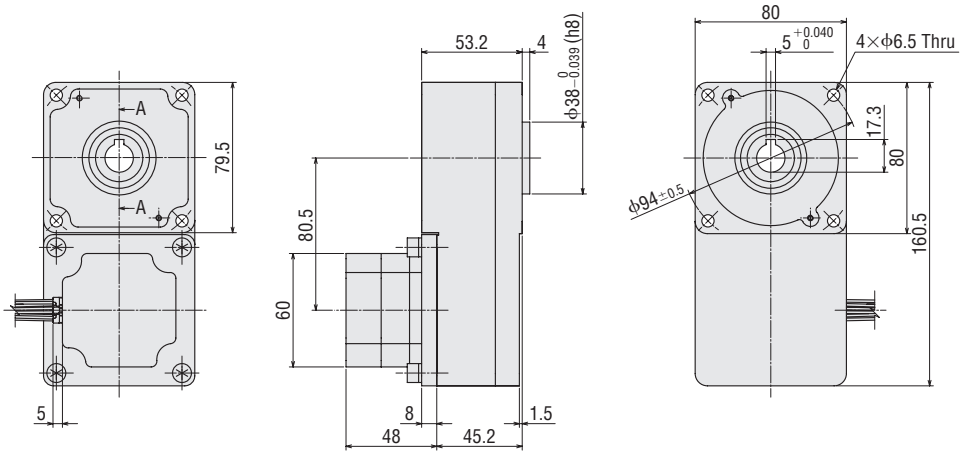
•Cable output in the opposite side of the output shaft



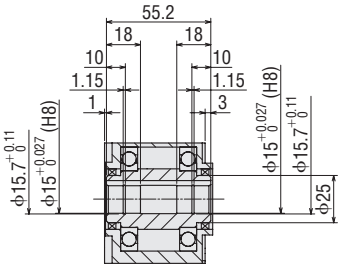
◇Hollow Shaft Flat Gearhead • 60 W

2D & 3D CAD

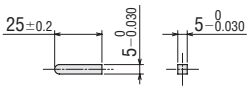
Product Name	Motor Product Name	Gearhead Product Name	Mass kg	2D CAD
BLMR460SHK-□FR	BLMR460SHK-GFV	GFS4G□FR	2.1	A1870



A-A



Parallel Key (Included)

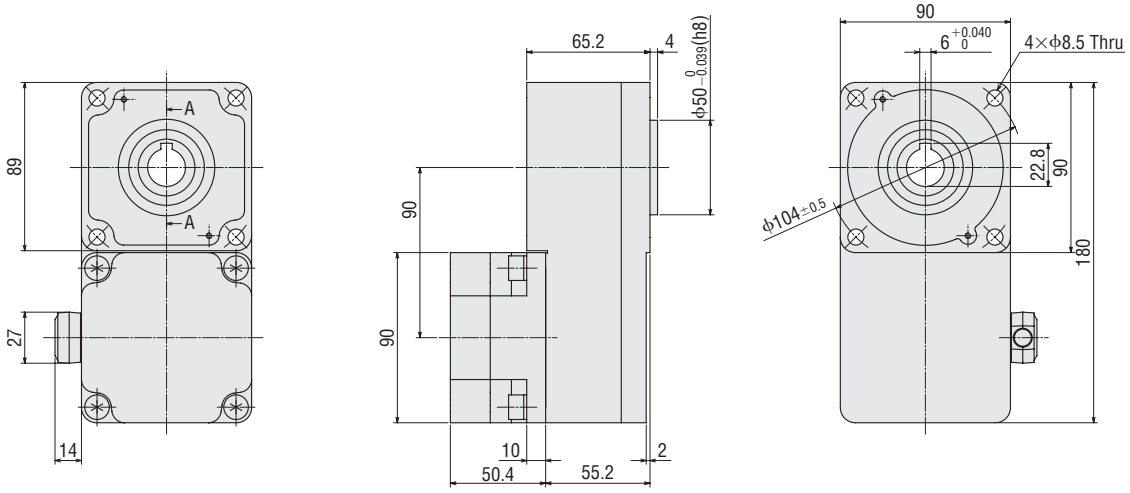


◇Hollow Shaft Flat Gearhead • 100 W

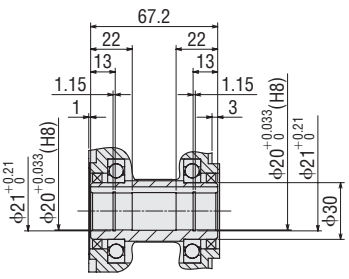
2D & 3D CAD

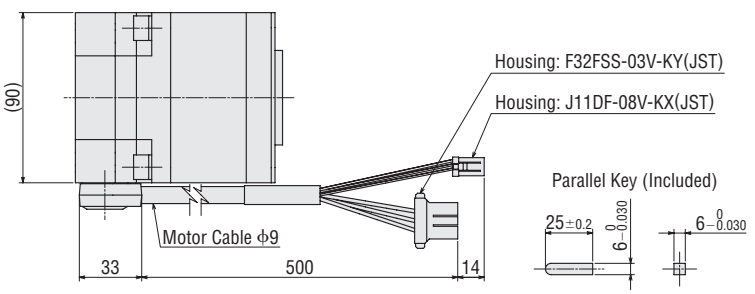
Product Name	Motor Product Name	Gearhead Product Name	Mass kg	2D CAD	
				Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR5100K-□FR-■	BLMR5100K-GFV-■	GFS5G□FR	3.3	A1809_F	A1809_B

•Cable output in the side of the output shaft



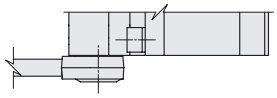
A-A





Parallel Key (Included)

•Cable output in the opposite side of the output shaft

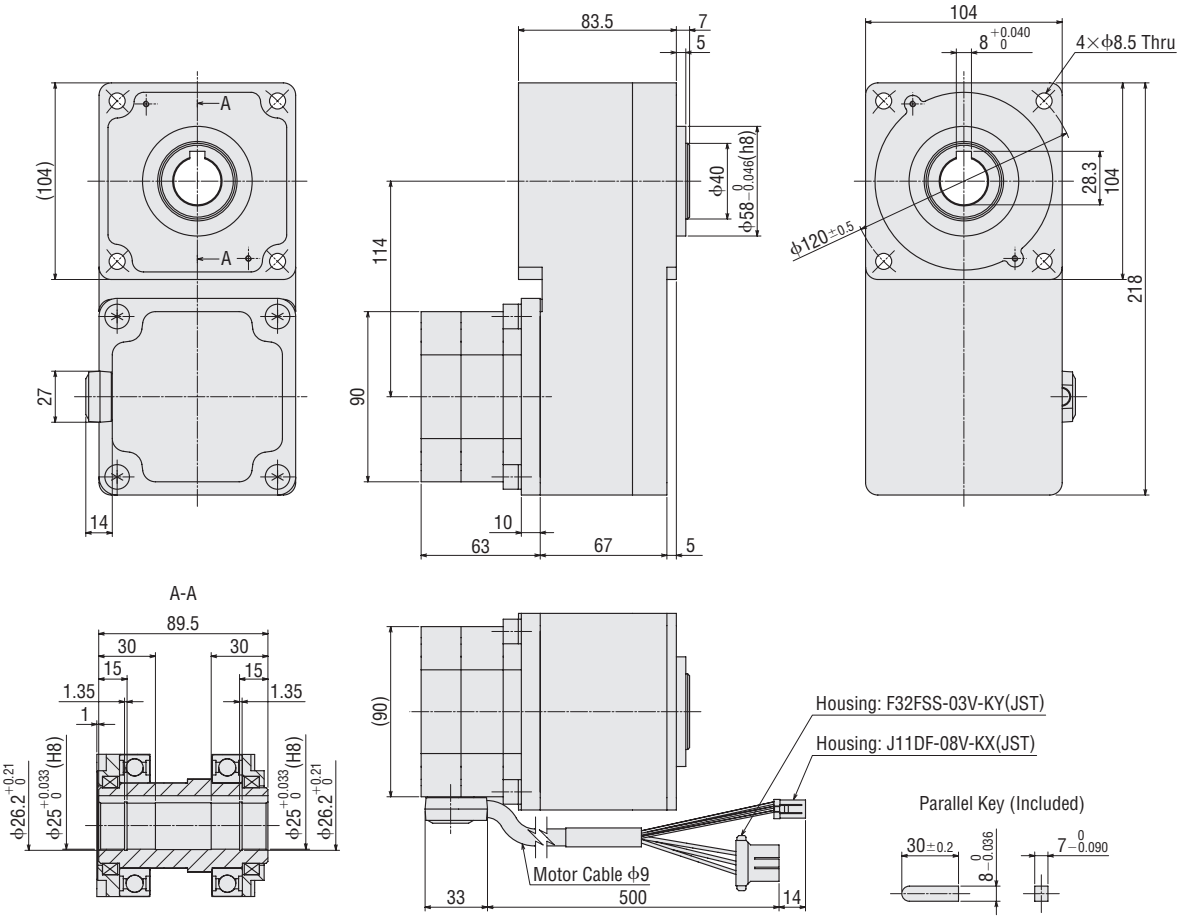


◇Hollow Shaft Flat Gearhead • 200 W

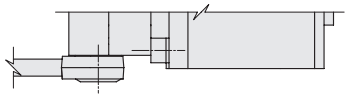
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Mass kg	2D CAD	
				Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR6200SK-□FR-■	BLMR6200SK-GFV-■	GFS6G□FR	6.5	A1815_F	A1815_B

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft

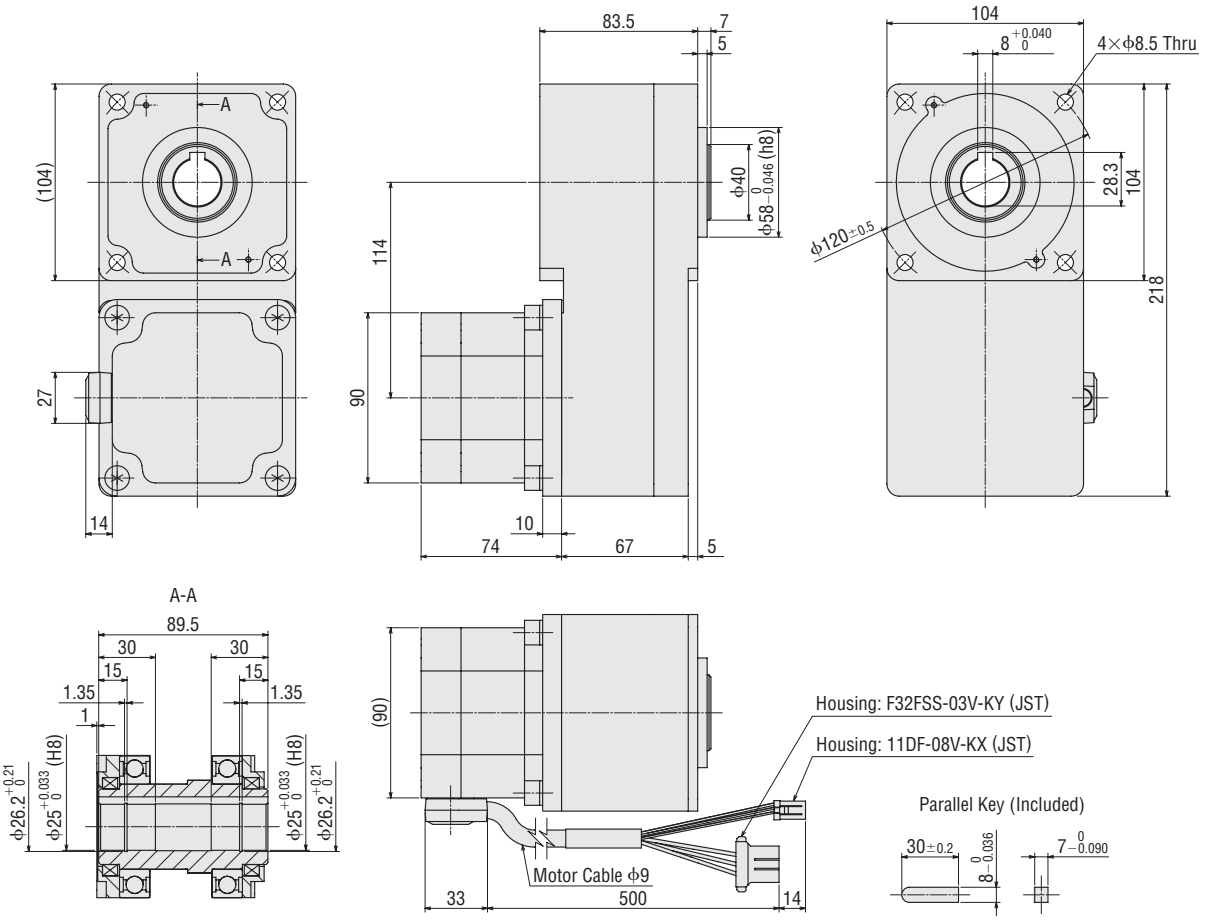


◇Hollow Shaft Flat Gearhead • 400 W

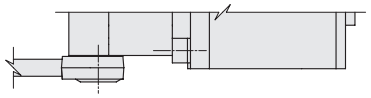
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Mass kg	2D CAD	
				Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR6400SK-□FR-■	BLMR6400SK-GFV-■	GFS6G□FR	6.9	A1858_F	A1858_B

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft

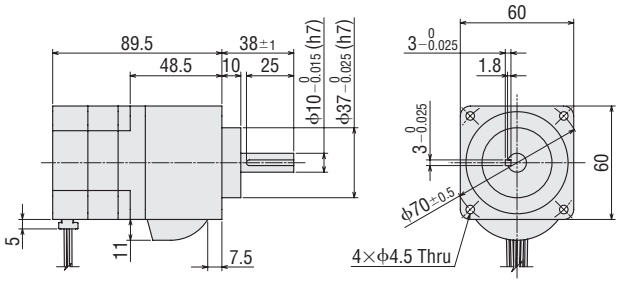


◇**CS** Geared Motor • 60 W

BLMR260HK-□CS

Mass: 0.87 kg

2D CAD A1871

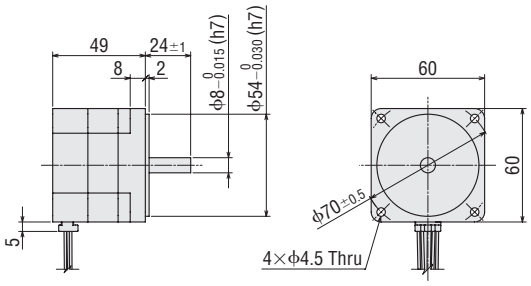


◇Round Shaft Type • 60 W

BLMR260HK-A

Mass: 0.47 kg

2D CAD A1872



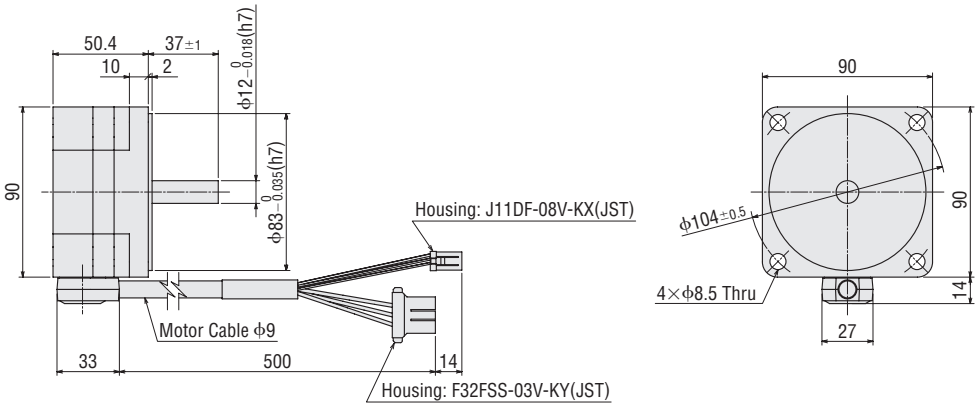
◇Round Shaft Type • 100 W

BLMR5100K-A-■

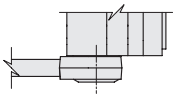
Mass: 1.1 kg

2D CAD Output in the side of the output shaft: A1810_F Output in the opposite side of the output shaft: A1810_B 3D CAD

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft



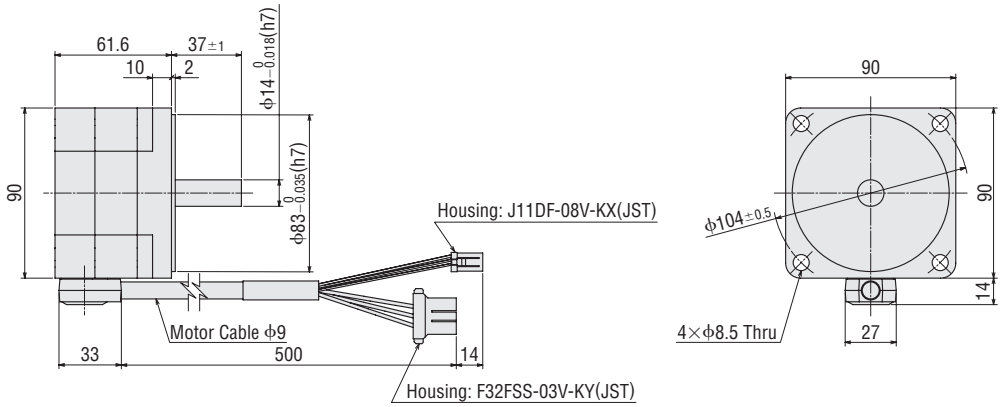
◇Round Shaft Type • 200 W

BLMR5200K-A-■

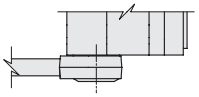
Mass: 1.6 kg

2D CAD Output in the side of the output shaft: A1816_F Output in the opposite side of the output shaft: A1816_B 3D CAD

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft



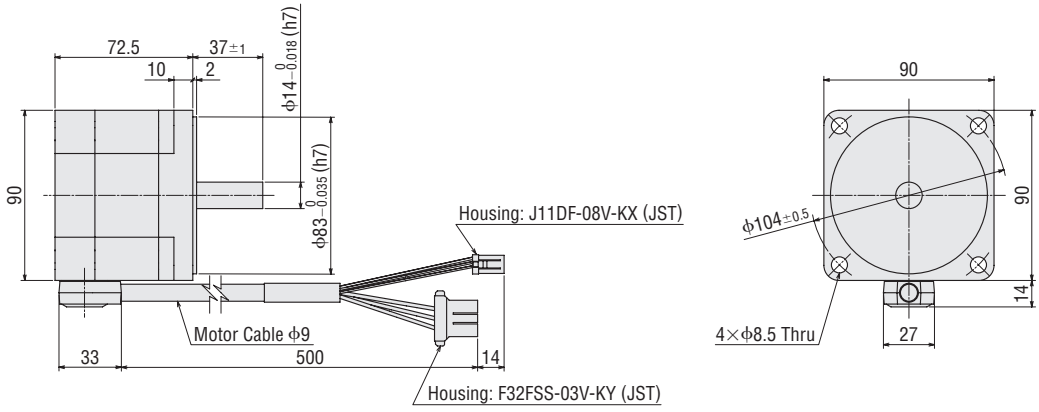
◇Round Shaft Type • 400 W

BLMR5400K-A-■

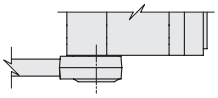
Mass: 2.0 kg

2D CAD Output in the side of the output shaft: A1859_F Output in the opposite side of the output shaft: A1859_B 3D CAD

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft



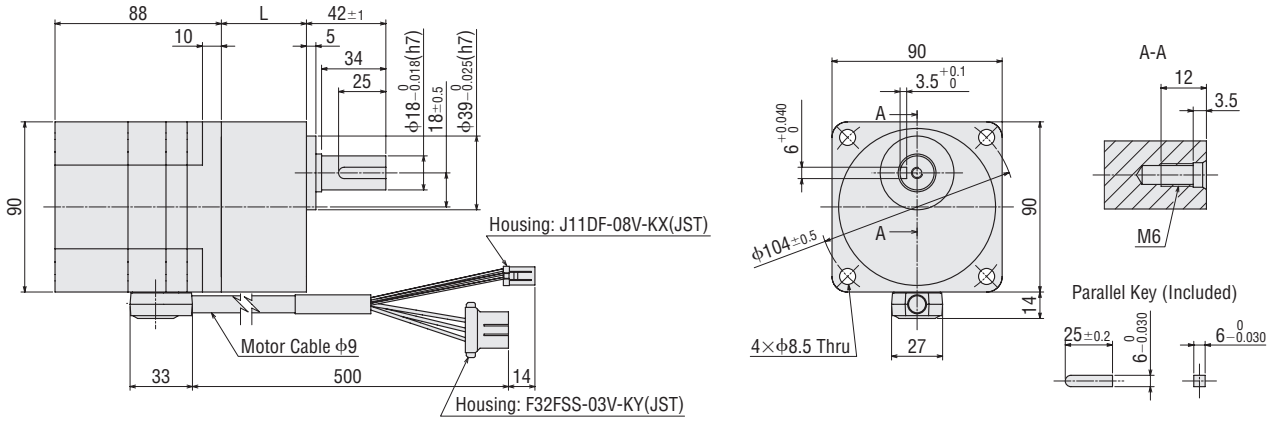
●Electromagnetic Brake Motor

◇Parallel Shaft Gearhead • 100 W

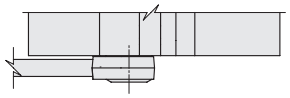
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	2D CAD	
						Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR5100KM-□-■	BLMR5100KM-GFV-■	GFV5G□	**10**～**20**	45	2.65	A1811A_F	A1811A_B
			30～**100**	58	3.0	A1811B_F	A1811B_B

●Cable output in the side of the output shaft



●Cable output in the opposite side of the output shaft

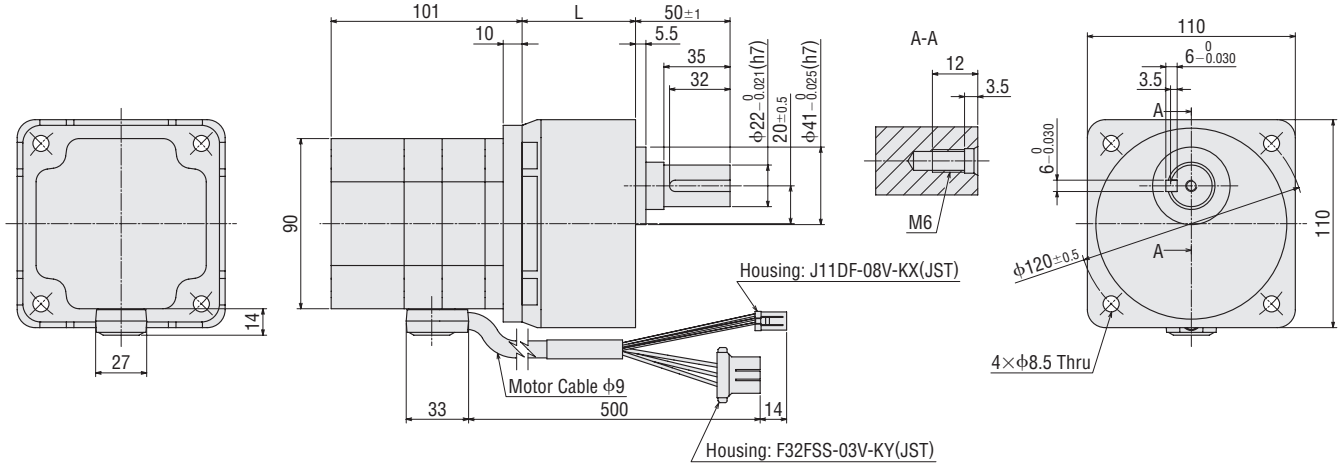


◇Parallel Shaft Gearhead • 200 W

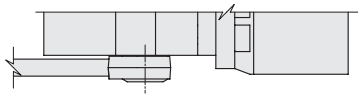
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	2D CAD	
						Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR6200SKM-□-■	BLMR6200SKM-GFV-■	GFV6G□	**10**～**20**	60	4.1	A1817A_F	A1817A_B
			30, **50**	72	4.6	A1817B_F	A1817B_B
			100	86	5.2	A1817C_F	A1817C_B

●Cable output in the side of the output shaft



●Cable output in the opposite side of the output shaft

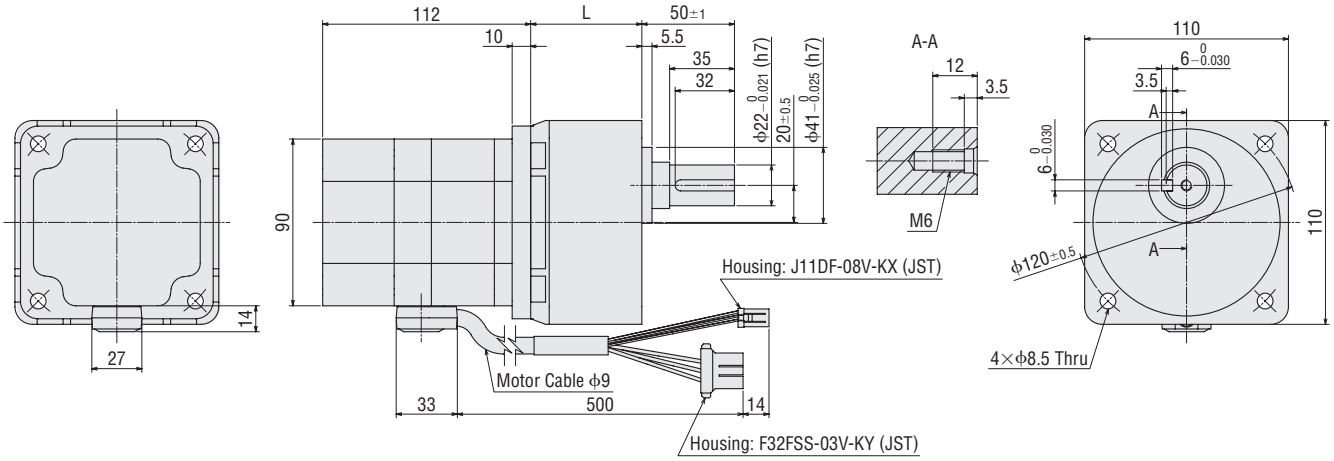


◇Parallel Shaft Gearhead • 400 W

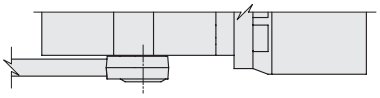
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	2D CAD	
						Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR6400SKM-□-■	BLMR6400SKM-GFV-■	GFV6G□	**10**～**20**	60	4.6	A1860A_F	A1860A_B
			30, **50**	72	5.1	A1860B_F	A1860B_B

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft

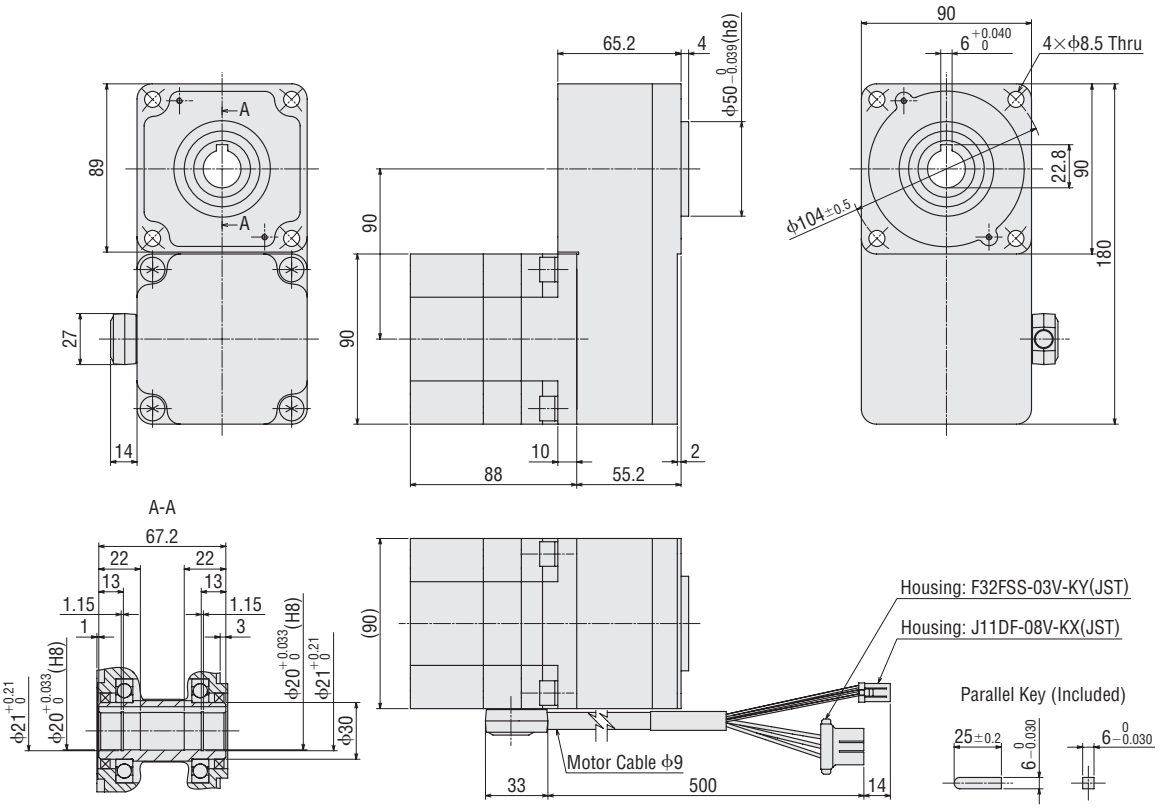


◇Hollow Shaft Flat Gearhead 100 W

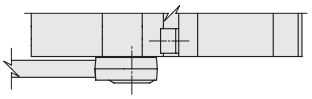
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Mass kg	2D CAD	
				Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR5100KM-□FR-■	BLMR5100KM-GFV-■	GFS5G□FR	3.9	A1812_F	A1812_B

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft

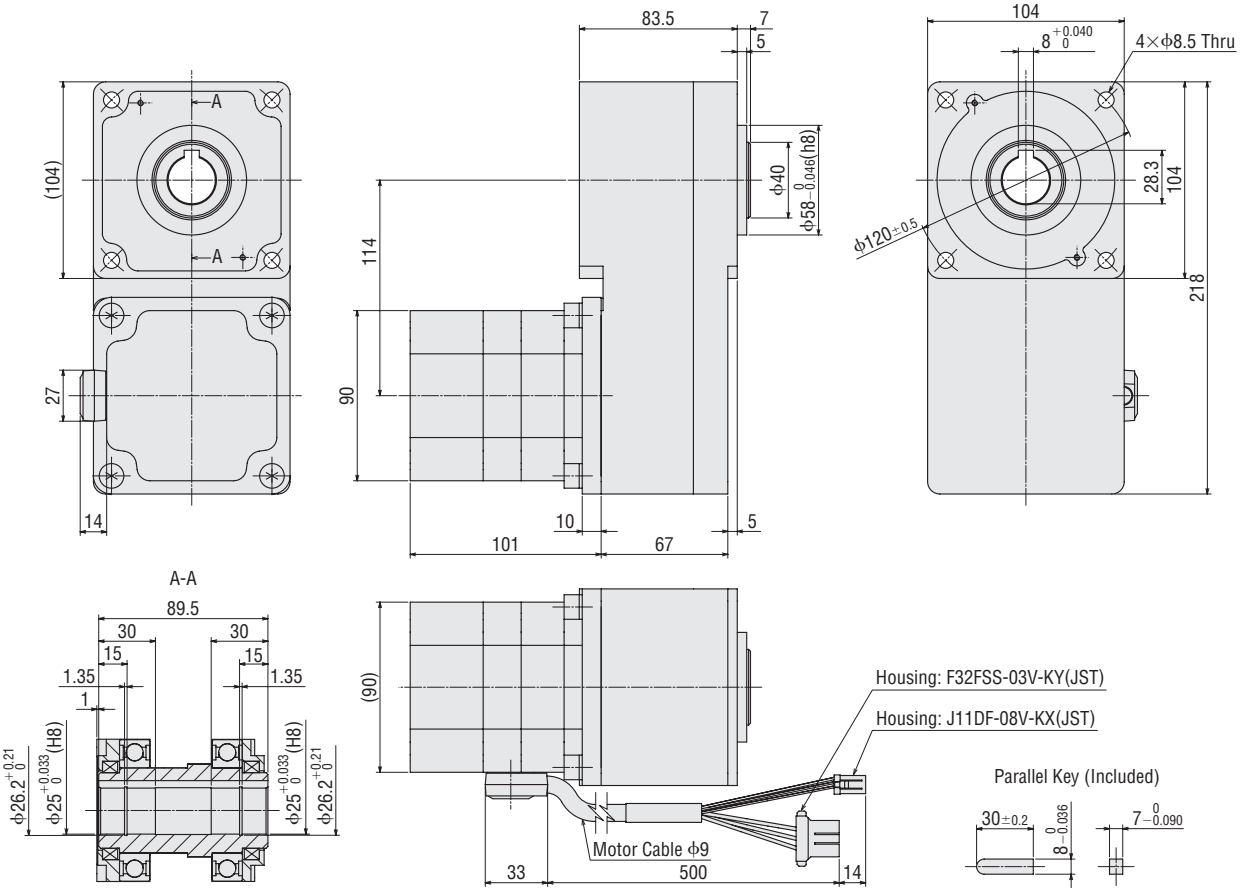


◇Hollow Shaft Flat Gearhead • 200 W

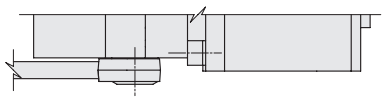
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Mass kg	2D CAD	
				Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR6200SKM-□FR-■	BLMR6200SKM-GFV-■	GFS6G□FR	7.0	A1818_F	A1818_B

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft

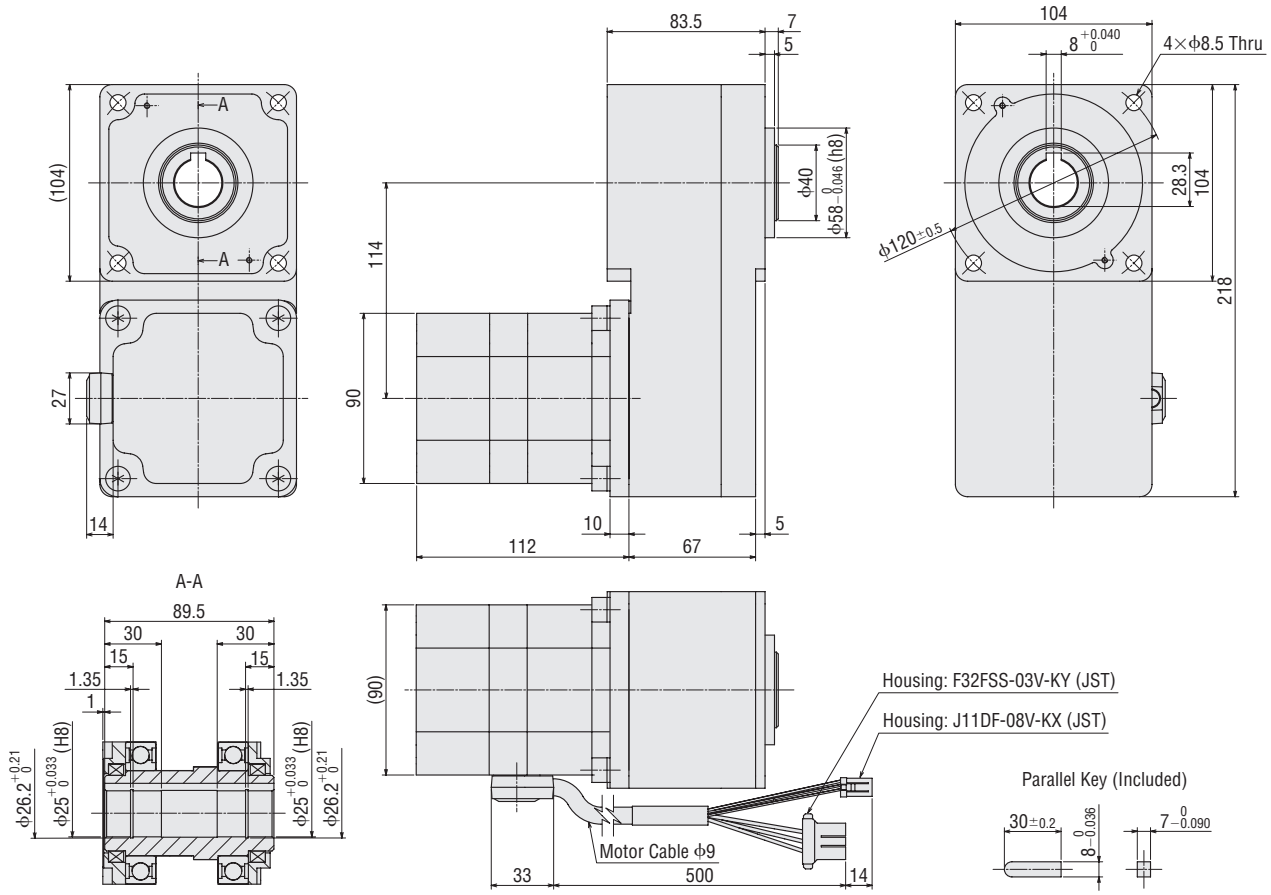


◇Hollow Shaft Flat Gearhead • 400 W

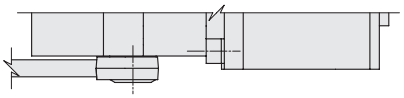
2D & 3D CAD

Product Name	Motor Product Name	Gearhead Product Name	Mass kg	2D CAD	
				Cable Output in the Side of the Output Shaft	Cable Output in the Opposite Side of the Output Shaft
BLMR6400SKM-□FR-■	BLMR6400SKM-GFV-■	GFS6G□FR	7.5	A1861_F	A1861_B

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft



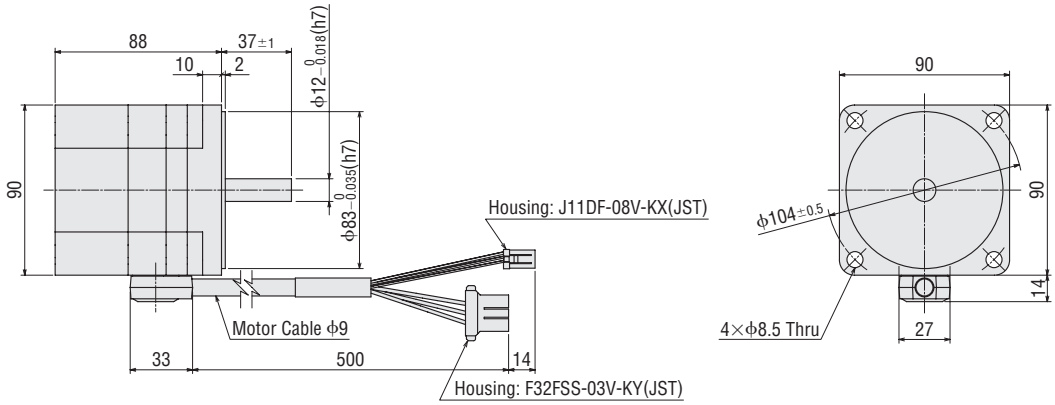
◇Round Shaft Type • 100 W

BLMR5100KM-A-■

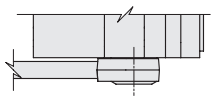
Mass: 1.7 kg

2D CAD Output in the side of the output shaft: A1813_F Output in the opposite side of the output shaft: A1813_B 3D CAD

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft



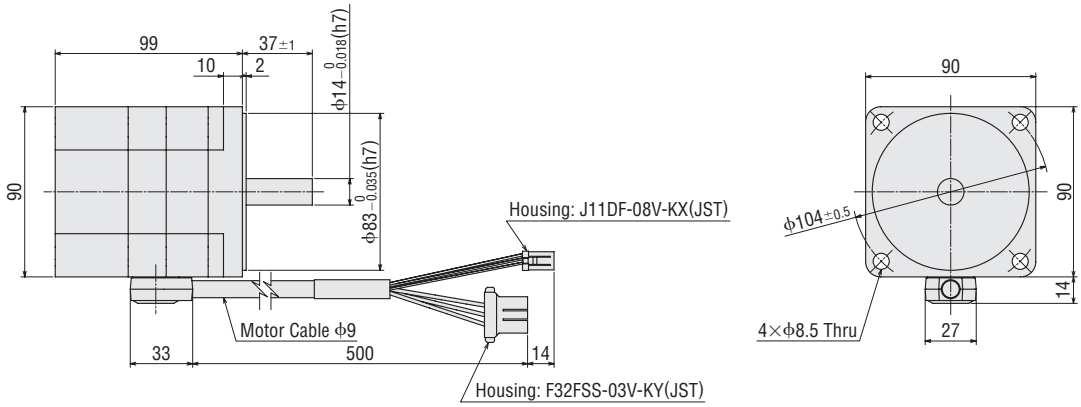
◇Round Shaft Type • 200 W

BLMR5200KM-A-■

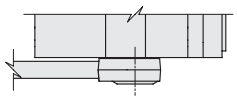
Mass: 2.1 kg

2D CAD Output in the side of the output shaft: A1819_F Output in the opposite side of the output shaft: A1819_B 3D CAD

•Cable output in the side of the output shaft



•Cable output in the opposite side of the output shaft



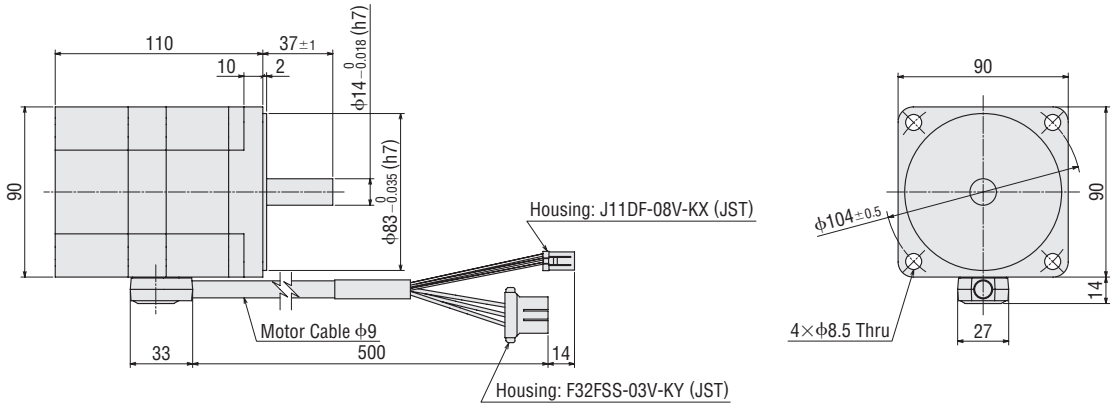
◇Round Shaft Type • 400 W

BLMR5400KM-A-■

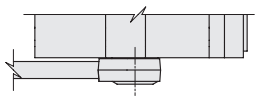
Mass: 2.6 kg

2D CAD Output in the side of the output shaft: A1862_F Output in the opposite side of the output shaft: A1862_B 3D CAD

- **Cable output in the side of the output shaft**



- **Cable output in the opposite side of the output shaft**

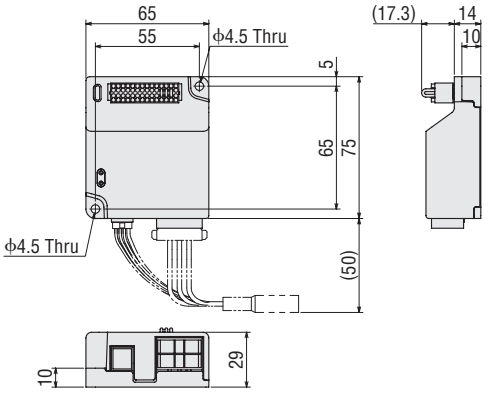


●Driver

BLVD-KRD

Mass: 0.12 kg

2D CAD A1806 3D CAD

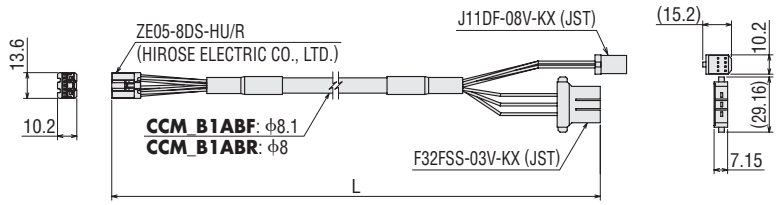


●Connection Cables / Flexible Connection Cables

◇For 60 W

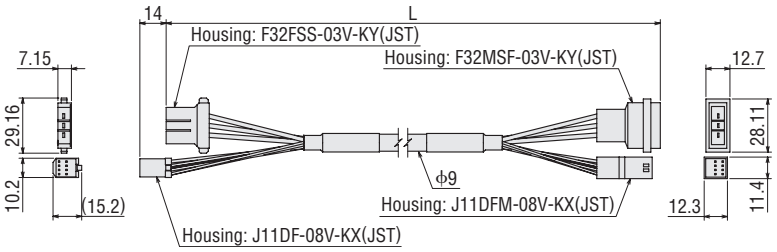
Product Line	Length L (m)	Product Name	Mass (kg)
Connection cable	0.3	**CCM003B1ABF**	0.03
	1	**CCM010B1ABF**	0.09
	2	**CCM020B1ABF**	0.18
	3	**CCM030B1ABF**	0.27
Flexible Connection Cable	1	**CCM010B1ABR**	0.09
	2	**CCM020B1ABR**	0.18
	3	**CCM030B1ABR**	0.27

Motor Side Driver Side



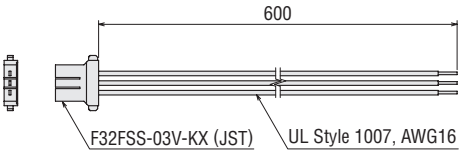
◇For 100 W, 200 W, and 400 W

Product Line	Length L (m)	Product Name	Mass (kg)
Connection cable	1	**CCM010B1AAF**	0.13
	2	**CCM020B1AAF**	0.25
	3	**CCM030B1AAF**	0.37
Flexible Connection Cable	1	**CCM010B1AAR**	0.14
	2	**CCM020B1AAR**	0.27
	3	**CCM030B1AAR**	0.40



●Power Supply Cable

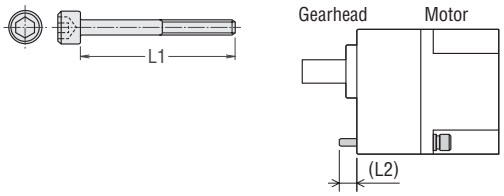
LC03D06A



Installation Screw Dimensions

L2 is the dimensions when a flat washer and spring washer are installed on the head side of the screw.

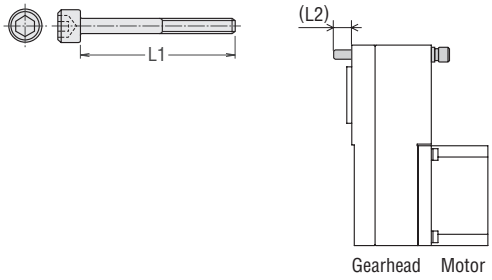
Parallel Shaft Gearhead



Product Name	Gear Ratio	Installation Screws		L2 (mm)
		Type of Screw	L1 (mm)	
GFV4G□	5~20	M6	60	8
	30~100		65	8
GFV5G□	10~20	M8	70	11.5
	30~100		85	13.5
GFV6G□	10~20	M8	85	11
	30, 50		100	14
	100		110	10
BLMR260HK-□CS	5~20	M4	60	10

● Installation screws: 4 flat washers and spring washers are included.
The material of the installation screws is stainless steel.

Hollow Shaft Flat Gearhead



Product Name	Gear Ratio	Installation Screws		L2 (mm)
		Type of Screw	L1 (mm)	
GFS4G□FR	5~200	M6	70	14
GFS5G□FR	10~200	M8	90	21
GFS6G□FR	10~100	M8	100	13

● Installation screws: 4 flat washers, spring washers and hexagonal nuts are included.
No hexagonal nuts are included with the GFS6G□FR.

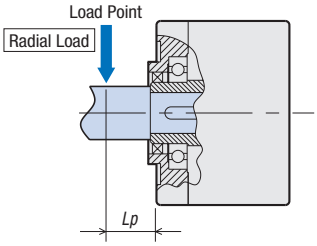
● A number indicating the gear ratio is specified where the box □ is located in the product name.

■Calculation of Permissible Radial Load of Hollow Shaft Flat Gearhead

The permissible radial load calculation formula differs depending on the mechanism.

◇If One Side of the Load Shaft is Not Supported by the Bearing Unit

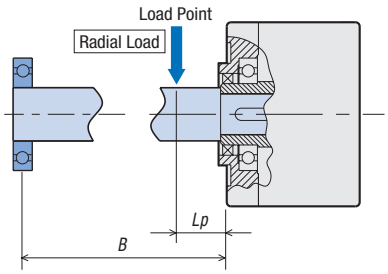
Radial load is the most severe mechanism. The recommended load shaft is the stepped type.



F_0 [N] : Permissible radial load on flange-installation surface
Lp [mm] : Distance from flange-installation surface to radial load point
B [mm] : Distance from flange-installation surface to bearing unit

Product Name	Permissible Radial Load W [N]
GFS4G□FR	$W[N]=\frac{40}{40+Lp}\times F_0[N]$
GFS5G□FR	$W[N]=\frac{50}{50+Lp}\times F_0[N]$
GFS6G□FR	$W[N]=\frac{60}{60+Lp}\times F_0[N]$

◇If One Side of the Load Shaft is Supported by the Bearing Unit



Product Name	Permissible Radial Load W [N]
GFS4G□FR GFS5G□FR GFS6G□FR	$W[N]=\frac{B}{B-Lp}\times F_0[N]$

Product Name	Speed	Gear Ratio	F_0 [N]
GFS4G□FR	At 1～3000 r/min	5, 10	1000
		15～200	1500
	At 4000 r/min	5, 10	910
		15～200	1370
GFS5G□FR	At 1～3000 r/min	10	1080
		15, 20	1550
		30～200	1800
	At 4000 r/min	10	980
		15, 20	1430
		30～200	1680
GFS6G□FR	At 1～3000 r/min	10	1430
		15, 20	1960
		30～100	2380
	At 4000 r/min	10	1320
		15, 20	1810
		30～100	2210

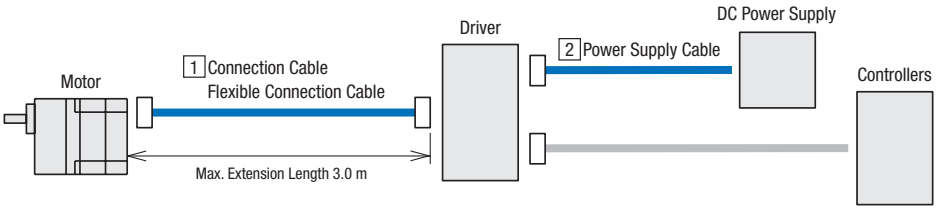
● A number indicating the gear ratio is specified where the box □ is located in the product name.

Cables / Peripheral Equipment (Sold separately)

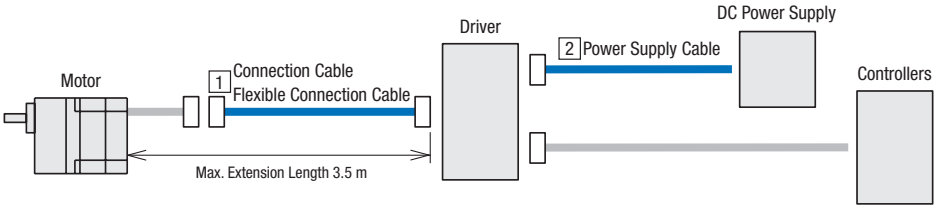
Cables

Cable System Configuration

◇60 W Type



◇100 W, 200 W, and 400 W Type



1 Connection Cables / Flexible Connection Cables

These cables are used to connect the motor and the driver.

- Keep the overall cable within 3.5 m (3.0 m for the 60 W type).
- Use the flexible connection cable in applications where the cable is bent and flexed repeatedly.

● Product Line → Page 16
● Dimensions → Page 40

2 Power Supply Cable

These cables are used to connect the driver and the DC power supply.

● Product Line → Page 16
● Dimensions → Page 40

Flange Drive Adapter

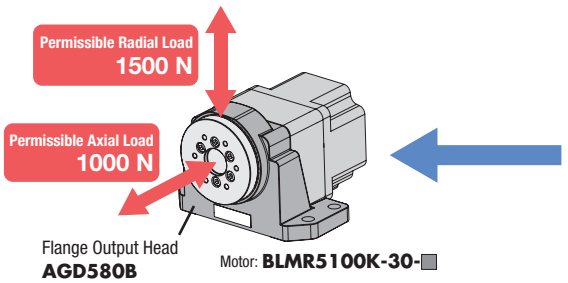
These products allow for increased permissible radial load and permissible axial load with the installation of a gearhead.
A cross-roller bearing is used for the bearing.
Because a wheel, rotary table, etc. can be directly installed on the rotating machine easily, this shortens the design time.

- For use with parallel shaft gearhead motors with an output power of 100 W.
- Refer to the product catalog (B-62) for details.

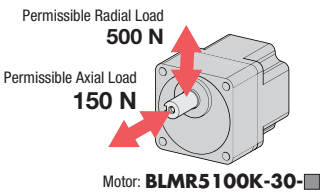
Product Line

Product Name	Applicable Product
AGD580B	**BLMR5100**

· When a flange output head is installed



· Parallel shaft gearhead only



- The letter **F** or **B** indicating the cable output direction is specified where the box □ is located in the product name.

✻The torque, speed, and rotation direction are the same as those for the parallel shaft gearhead being installed.

Mounting Bracket for Motor and Gearhead

A convenient mounting bracket for installing and fixing parallel shaft gearheads and round shaft types.

Product Line

Product Name	Applicable Product
SOL2M4F	**BLMR260** (**CS** geared motor, round shaft type)
SOL4M6F	**BLMR460** (Parallel shaft gearhead)
SOL5M8F	**BLMR5100** **BLMR5200**, **BLMR5400** (Round shaft type)
SOL6M8F	**BLMR6200**, **BLMR6400** (Parallel shaft gearhead)

Note

- A hollow shaft flat gearhead cannot be used.

Flexible Couplings

A clamp type coupling for connecting the motor and gearhead shaft.
Couplings that can be used with parallel shaft gearheads and round shaft types are available.

- Couplings can also be used on round shaft types.
  Select a coupling with the same inner diameter as the motor shaft diameter.

Product Line

Applicable Product	Load Type	Coupling Type
BLMR460	Uniform Load	**MCL40** Type
	Impact Load	**MCL55** Type
BLMR5100	Uniform Load	**MCL55** Type
	Impact Load	
BLMR6200 **BLMR6400**	Uniform Load	**MCL65** Type
	Impact Load	

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